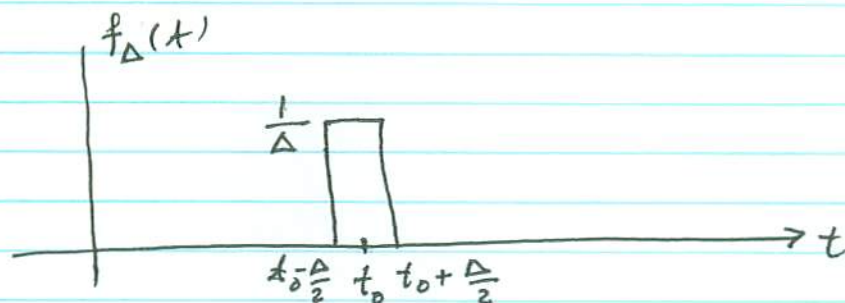


Lecture 11, August 8, 2006

A strange "function":

Consider the following function



That is:

$$f_{\Delta}(t) = \begin{cases} 0 & t < t_0 - \frac{\Delta}{2} \\ \frac{1}{\Delta} & t_0 - \frac{\Delta}{2} \leq t \leq t_0 + \frac{\Delta}{2} \\ 0 & t > t_0 + \frac{\Delta}{2} \end{cases}$$

Take integral of  $f_{\Delta}(t)$

$$\int_{-\infty}^{\infty} f_{\Delta}(t) dt = \int_{t_0 - \frac{\Delta}{2}}^{t_0 + \frac{\Delta}{2}} \frac{1}{\Delta} dt = 1$$

note that the integral is equal to 1  
irrespective of the value of  $\Delta$ .

Now, let  $\Delta \rightarrow 0$ . Then,  $f_{\Delta}(t)$  would  
be zero everywhere except at  $t = t_0$  where  
it is equal to  $\infty$ . But still its integral is  
equal to one. This limiting function is  
called Dirac's delta function.

$$\lim_{\Delta \rightarrow 0} f_{\Delta}(x) = \delta(x - t_0) = \begin{cases} \infty & x \neq t_0 \\ 0 & x = t_0 \end{cases}$$

But

$$\int_{-\infty}^{\infty} \delta(x - t_0) dt = 1$$

Now, let  $f(x)$  be an arbitrary function.

$$f(x) f_{\Delta}(x) = \begin{cases} \frac{1}{\Delta} f(x) & t_0 - \frac{\Delta}{2} \leq x \leq t_0 + \frac{\Delta}{2} \\ 0 & \text{elsewhere} \end{cases}$$

$$\int_{-\infty}^{\infty} f(x) f_{\Delta}(x) dx = \int_{t_0 - \frac{\Delta}{2}}^{t_0 + \frac{\Delta}{2}} \frac{1}{\Delta} f(x) dx$$

When  $\Delta$  is very small  $f(x) \cong f(t_0)$ ,  $t_0 - \frac{\Delta}{2} \leq x \leq t_0 + \frac{\Delta}{2}$

$$\text{So, } \int_{-\infty}^{\infty} f(x) f_{\Delta}(x) dx = \frac{1}{\Delta} \int_{t_0 - \frac{\Delta}{2}}^{t_0 + \frac{\Delta}{2}} f(t_0) dt_0 = f(t_0)$$

So, as  $\Delta \rightarrow 0$

$$\int_{-\infty}^{\infty} f(x) \delta(x - t_0) dx = f(t_0)$$

This is called the sifting property of the delta function.

Note that we do not need to have integral extended from  $-\infty$  to  $\infty$ .

Integral between any two values  $a$  and  $b$  is equal to  $f(t_0)$  as long as  $a < t_0 < b$

$$\int_a^b f(t) \delta(t-t_0) dt = f(t_0) \quad \text{if } a < t_0 < b$$

but,

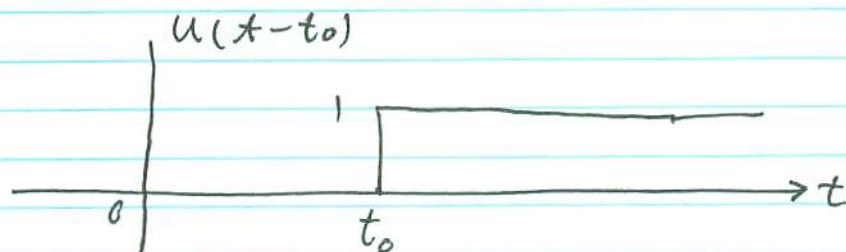
$$\int_a^b f(t) \delta(t-t_0) dt = 0$$

if either  $a \leq b < t_0$  or  $t_0 < a \leq b$ .

$\delta(t-t_0)$  is also called an impulse function.

Note that

$$\int_{-\infty}^t \delta(x'-t_0) dx' = \begin{cases} 0 & t < t_0 \\ 1 & t > t_0 \end{cases} = u(t-t_0)$$



This is called the unit step function.

So

$$\int_{-\infty}^t \delta(x' - t_0) dt' = u(x - t_0)$$

and

$$\frac{d}{dt} u(x - t_0) = \delta(x - t_0)$$

When  $t_0 = 0$ , we have

$$\int_{-\infty}^{\infty} \delta(x') dt' = u(x)$$

and

$$\frac{d}{dt} u(x) = \delta(x).$$

Example: Evaluate the following integral

$$\int_{-\infty}^{\infty} (t^2 + 3t + 5) \delta(t - 2) dt$$

$$\begin{aligned} \int_{-\infty}^{\infty} (t^2 + 3t + 5) \delta(t - 2) &= (t^2 + 3t + 5) \Big|_{t=2} \\ &= 2^2 + 3 \times 2 + 5 = 15 \end{aligned}$$

## The Convolution / Linear-Time-Invariant Systems

Recall that

$$\int_{-\infty}^{\infty} f(t) \delta(t - t_0) dt = f(t_0)$$

replace  $t$  by  $\tau$  to get

$$\int_{-\infty}^{\infty} f(\tau) \delta(\tau - t_0) d\tau = f(t_0)$$

Substituting  $t$  for  $t_0$ , we get,

$$\int_{-\infty}^{\infty} f(\tau) \delta(t - \tau) d\tau = f(t)$$

where, we have used the fact that

$$\delta(t - \tau) = \delta(\tau - t).$$

Note that, the equation

$$f(t) = \int_{-\infty}^{\infty} f(\tau) \delta(t - \tau) d\tau$$

indicates that  $f(t)$  can be represented as an infinite sum of delta functions each weighted by the value of  $f(t)$  at the center

of the delta function.

Now assume that we have a system that inputs a function (say a waveform),  $x(t)$  and outputs another waveform  $y(t)$ .



That is

$$T[x(t)] = y(t)$$

A system is called linear if its output for sum of two inputs is equal to sum of the two outputs to those two inputs, i.e.,

$$T[a_1 x_1(t) + a_2 x_2(t)] = a_1 T[x_1(t)] + a_2 T[x_2(t)]$$

A system is called time-invariant if its output to a shifted version of a waveform is a shifted version of its output to that input.

That is, if

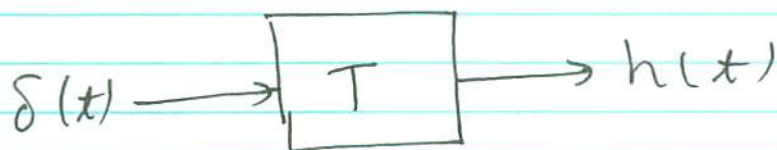
$$T[x(t)] = y(t)$$

then  $T[x(t-t_0)] = y(t-t_0)$

We saw that any function can be written as a sum of delta functions. So, for a linear time-invariant system, if we know the output for a delta (impulse) function, then we can find the output for any arbitrary function. That is if we have

$$T[\delta(t)] = h(t)$$

or



$h(t)$  is called the impulse response of the system

then

$$y(t) = T[x(t)] = T\left[\int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau\right]$$

$$= \int_{-\infty}^{\infty} x(\tau) T[\delta(t-\tau)] d\tau$$

$$= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau = x(t) * h(t)$$

This is called the convolution of  $x(t)$  and  $h(t)$ .

If  $x(t)$  is causal, i.e.,  $x(t) = 0, t < 0$   
then,

$$y(t) = \int_0^{\infty} x(\tau) h(t-\tau) d\tau$$

also if  $h(t)$  is causal, i.e.,  $h(t) = 0$   
for  $t < 0$  then

$$h(t-\tau) = 0 \text{ for } t-\tau < 0 \\ \text{or } \tau > t.$$

So:

$$y(t) = \int_0^t x(\tau) h(t-\tau) d\tau = x(t) * h(t)$$

### The Laplace Transforms

Laplace transform is used to turn a convolution into a multiplication of two functions. It is also used to solve differential Equations into algebraic equations and making the solution of differential equations easy.



Definition: Let  $f(t)$  be a function defined for  $t \geq 0$ . Then

$$F(s) = \mathcal{L}[f(t)] = \int_0^{\infty} e^{-st} f(t) dt$$

is called the Laplace transform of  $f(t)$ , provided that the integral exists.

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Example: Find the Laplace transform of  $\delta(t)$

$$\mathcal{L}[\delta(t)] = \int_0^{\infty} e^{-st} \delta(t) dt = e^{-st} \Big|_{t=0} = 1$$

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Example: Find the Laplace transform of  $u(t)$ .

Remember

$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t \leq 0 \end{cases}$$

$$\mathcal{L}[u(t)] = \int_0^{\infty} e^{-st} dt = -\frac{1}{s} e^{-st} \Big|_0^{\infty} = -\frac{1}{s} [0 - 1] = \frac{1}{s}$$

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Example: Find the Laplace transform of

$$f(t) = t$$

Note: here we mean ~~f(t) = t~~  $f(t) = t$  for  $t > 0$  and  $f(t) = 0$  for  $t < 0$ . So, it would be more formal if we write:

$$f(t) = t u(t).$$

Solution

$$\begin{aligned} \mathcal{L}[t] &= \int_0^{\infty} t e^{-st} dt = \frac{-t e^{-st}}{s} \Big|_0^{\infty} + \frac{1}{s} \int_0^{\infty} e^{-st} dt \\ &= \frac{1}{s} \times \frac{e^{-st}}{s} \Big|_0^{\infty} = \frac{1}{s^2} \end{aligned}$$

Example: Evaluate  $\mathcal{L}\{e^{-3t}\}$

$$\begin{aligned} \mathcal{L}\{e^{-3t}\} &= \int_0^{\infty} e^{-3t} e^{-st} dt = \int_0^{\infty} e^{-(3+s)t} dt \\ &= \frac{-1}{s+3} e^{-(s+3)t} \Big|_0^{\infty} = \frac{1}{s+3} \end{aligned}$$

for  $s > -3$ .

Example: Find the Laplace transform of

$$f(t) = \sin \omega t$$

$$\mathcal{L}[\sin \omega t] = \int_0^{\infty} \sin \omega t e^{-st} dt$$

$$= \int_0^{\infty} \frac{e^{i\omega t} - e^{-i\omega t}}{2i} e^{-st} dt$$

$$= \frac{1}{2i} \int_0^{\infty} e^{(i\omega - s)t} dt - \frac{1}{2i} \int_0^{\infty} e^{-(i\omega + s)t} dt$$

$$= \frac{1}{2i} \left[ \frac{1}{i\omega - s} e^{(i\omega - s)t} \right]_0^{\infty} + \frac{1}{2i} \left[ \frac{1}{i\omega + s} e^{-(i\omega + s)t} \right]_0^{\infty}$$

if  $s > 0$

$$= \frac{1}{2i} \frac{1}{i\omega - s} (-1) + \frac{1}{2i} \frac{1}{i\omega + s} (-1)$$

$$= -\frac{1}{2i} \left[ \frac{1}{i\omega - s} + \frac{1}{i\omega + s} \right]$$

$$= -\frac{1}{2i} \left[ \frac{i\omega + s + i\omega - s}{-s^2 + \omega^2} \right] = \frac{2\omega}{s^2 + \omega^2}$$

Example: Find the Laplace transform of

$$f(t) = \cos \omega t$$

$$\mathcal{L}[\cos \omega t] = \int_0^{\infty} \cos \omega t e^{-st} dt = \int_0^{\infty} \frac{e^{i\omega t} + e^{-i\omega t}}{2} e^{-st} dt$$

$$= \frac{1}{2} \int_0^{\infty} e^{-(s-i\omega)t} dt + \frac{1}{2} \int_0^{\infty} e^{-(s+i\omega)t} dt$$

$$= \frac{1}{2} \left. \frac{-1}{s-i\omega} e^{-(s-i\omega)t} \right|_0^{\infty} + \frac{1}{2} \left. \frac{-1}{s+i\omega} e^{-(s+i\omega)t} \right|_0^{\infty}$$

$$= \frac{-1}{2} \frac{1}{s-i\omega} (0-1) - \frac{1}{2} \frac{1}{s+i\omega} (0-1)$$

$$= \frac{1}{2} \left[ \frac{1}{s-i\omega} + \frac{1}{s+i\omega} \right] = \frac{1}{2} \frac{2s}{s^2 + \omega^2}$$

$$= \boxed{\frac{s}{s^2 + \omega^2}}$$

Example: Find the Laplace transform of

$$f(t) = 1 + 5t$$

$$\mathcal{L}[1 + 5t] = \mathcal{L}[1] + 5\mathcal{L}[t]$$

$$= \boxed{\frac{1}{s} + \frac{5}{s^2}}$$

In the above example, we used the linearity of Laplace transform. That is:

$$\begin{aligned}\mathcal{L}[af(x)+bg(x)] &= \int_0^{\infty} [af(x)+bg(x)]e^{-st} dt \\ &= a \int_0^{\infty} f(x)e^{-st} dt + b \int_0^{\infty} g(x)e^{-st} dt \\ &= a \mathcal{L}[f(x)] + b \mathcal{L}[g(x)]\end{aligned}$$

Laplace transform of some basic functions:

- 1)  $\mathcal{L}[c] = \frac{c}{s}$  in particular  $\mathcal{L}[1] = \frac{1}{s}$
- 2)  $\mathcal{L}[x] = \frac{1}{s^2}$
- 3)  $\mathcal{L}[x^2] = \frac{2}{s^3}$
- 4) in general,  $\mathcal{L}[x^n] = \frac{n!}{s^{n+1}}$
- 5)  $\mathcal{L}[\sin \omega t] = \frac{\omega}{s^2 + \omega^2}$
- 6)  $\mathcal{L}[\cos \omega t] = \frac{s}{s^2 + \omega^2}$
- 7)  $\mathcal{L}[\sinh(\omega t)] = \frac{\omega}{s^2 - \omega^2}$
- 8)  $\mathcal{L}[\cosh(\omega t)] = \frac{s}{s^2 - \omega^2}$

Definition: A function  $f(x)$  is said to be of exponential order  $c$  if there exist constants  $c, M > 0$  and  $T > 0$  such that

$$|f(x)| \leq M e^{ct} \text{ for all } x > T.$$

Example  $f(x) = x$

$$|x| \leq e^x \text{ for all } x > 0$$

So  $f(x) = x$  is of exponential order  $c = 1$ .

Example:  $f(x) = 2 \cos x$

$$|2 \cos x| \leq 2 e^x \text{ all } x > 0$$

So  $2 \cos x$  is of exponential order  $c = 1$ .

Example:  $f(x) = x^n$

$$|x^n| \leq M e^{ct} \text{ since } \left| \frac{x^n}{e^{ct}} \right| \leq M \text{ for some } M > 0$$

This can be shown by using L'Hôpital's rule.

Example:  $f(x) = e^{x^2}$  is not of exponential order since it grows faster than any  $e^{ct}$ .

Theorem: Sufficient Conditions for existence of Laplace Transform.

If  $f(t)$  is piecewise continuous on the interval  $[0, \infty)$  and of exponential order  $c$  for  $t > T$ , then  $\mathcal{L}[f(t)]$  exists for  $s > c$ .

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