

ANTIMATROIDS, BETWEENNESS, CONVEXITY

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1 Introduction

Korte and Lovász [12, 13] founded the theory of *greedoids*. These combinatorial structures characterize a class of optimization problems that can be solved by greedy algorithms. In particular, greedoids generalize *matroids*, introduced earlier by Whitney [16]. *Antimatroids*, introduced by Dilworth [3] as particular examples of semimodular lattices, make up another class of greedoids.

Antimatroids are related to abstract convexity; let us explain how. Kay and Womble [11] defined a *convexity space* on a ground set E as a tuple (E, \mathcal{N}) , where \mathcal{N} is a collection of subsets of E such that $\emptyset \in \mathcal{N}$, $E \in \mathcal{N}$, and \mathcal{N} is closed under intersections. Members of \mathcal{N} are called *convex sets*. The *convex hull* of a subset X of E is defined as the intersection of all convex supersets of X and is denoted by $\tau_{\mathcal{N}}(X)$. Independently of each other, Edelman [6] and Jamison [9] initiated the study of convexity spaces (E, \mathcal{N}) with the *anti-exchange property*

if $X \subseteq E$ and y, z are distinct points outside $\tau_{\mathcal{N}}(X)$,
then at most one of $y \in \tau_{\mathcal{N}}(X \cup \{z\})$ and $z \in \tau_{\mathcal{N}}(X \cup \{y\})$ holds true.

Jointly [7], they proposed to call such convexity spaces *convex geometries*. An antimatroid is a tuple (E, \mathcal{F}) such that $(E, \{E - X : X \in \mathcal{F}\})$ is a convex geometry.

In the present paper, we deal exclusively with finite ground sets. Our starting point are two examples of antimatroids. One of these arises from double shelling of a poset (example 2.4 in Chapter III of the monograph [14]) and the other from simplicial shelling of a triangulated graph (example 2.7 in Chapter III of [14]). Let us describe them in terms of convex geometries.

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In the first example, given a partially ordered set (E, \preceq) , we let \mathcal{N} consist of all subsets K of E such that

$$a, c \in K, a \prec b \prec c \Rightarrow b \in K;$$

the resulting tuple (E, \mathcal{N}) is a convex geometry. In the second example, given an undirected graph with a vertex-set E , we let \mathcal{N} consist of all subsets K of E such that

$$a, c \in K, b \text{ is an interior vertex of a chordless path from } a \text{ to } c \Rightarrow b \in K.$$

The resulting tuple (E, \mathcal{N}) is a convexity space, but not necessarily a convex geometry: for instance, take a chordless cycle through four vertices as the graph and consider the convex set X consisting of two adjacent vertices in this graph. Nevertheless, if the graph is *triangulated*, meaning that it contains no chordless cycle through four or more vertices, then (E, \mathcal{N}) is a convex geometry. To elucidate this point, we appeal to a characterization of convex geometries that involves the notion of an *extreme point* of a convex set K , defined as a point b of K such that $K - \{b\}$ is convex.

Nine equivalent characterizations of convex geometries are stated in [9]; equivalence of the following four is proved in [14], Chapter III, Theorem 1.1.

Fact 1. *For every convexity space (E, \mathcal{N}) , the following four propositions are logically equivalent:*

- (G1) (E, \mathcal{N}) has the anti-exchange property.
- (G2) If $X \in \mathcal{N}$ and $X \neq E$, then $X \cup \{y\} \in \mathcal{N}$ for some y in $E - X$.
- (G3) Every set in \mathcal{N} is the convex hull of its extreme points.
- (G4) Every subset X of E contains a unique minimal subset Y such that $\tau_{\mathcal{N}}(Y) = \tau_{\mathcal{N}}(X)$.

□

To see that our second example has property (G3), we invoke a theorem of Dirac [4]. There, a vertex is called *simplicial* if its neighbours are pairwise adjacent.

Fact 2. *For every finite undirected graph G , the following three propositions are logically equivalent:*

- G is triangulated.
- Every minimal cutset in G is a clique.
- Every induced subgraph of G either includes two nonadjacent simplicial vertices or is complete.

□

A corollary of this theorem (stated and proved in [8] as Theorem 3.2) asserts that

*every non-simplicial vertex in a triangulated graph
lies on a chordless path between two simplicial vertices;*

since the extreme points of E in the second example are precisely the simplicial vertices of G , it follows that every point of E lies in the convex hull of at most two extreme points of E .

Each of these two examples of convex geometries is constructed through the intermediary of betweenness in the underlying structure. In the first example, we may say that b lies between a and c if, and only if, $a \prec b \prec c$ or $c \prec b \prec a$; in the second example, we may say that b lies between a and c if, and only if, b is an interior vertex of a chordless path from a to c ; in either case, a subset K of E is convex if and only if

$$a, c \in K, b \text{ lies between } a \text{ and } c \Rightarrow b \in K.$$

This construction generalizes: as in [1], every ternary relation \mathcal{B} on a finite ground set E defines a convexity space $(E, \mathcal{N}_{\mathcal{B}})$ by

$$\mathcal{N}_{\mathcal{B}} = \{K \subseteq E : a, c \in K, (a, b, c) \in \mathcal{B} \Rightarrow b \in K\}.$$

Our objective is to characterize a nested pair of classes of ternary relations \mathcal{B} on finite ground sets E such that the corresponding classes of convexity spaces $(E, \mathcal{N}_{\mathcal{B}})$ consist exclusively of convex geometries, include all convex geometries that arise from double shelling of a poset, and include all convex geometries that arise from simplicial shelling of a triangulated graph.

2 Results

Note that, for every ternary relation \mathcal{B} on a finite ground set, every set K in $\mathcal{N}_{\mathcal{B}}$, and every point b of K ,

$$K - \{b\} \in \mathcal{N}_{\mathcal{B}} \Leftrightarrow \text{there are no points } a, c \text{ of } K \text{ such that } (a, b, c) \in \mathcal{B}.$$

This observation allows us to extend the definition of extreme points: given an arbitrary, not necessarily convex, subset X of the ground set and given an arbitrary point b of X , we shall say that b is an *extreme point of X* if, and only if, there are no points a, c of X such that $(a, b, c) \in \mathcal{B}$. The set of all extreme points of X will be denoted by $\text{ex}_{\mathcal{B}}(X)$.

In addition, note that $\mathcal{N}_{\mathcal{B}}$ does not change if \mathcal{B} is made symmetric by including (c, b, a) in \mathcal{B} whenever (a, b, c) is in \mathcal{B} ; it does not change either if all triples (b, b, b) , (b, b, c) , (a, b, b) are removed from \mathcal{B} . Note also that $\mathcal{N}_{\mathcal{B}}$ includes all singletons $\{a\}$ with $a \in E$ (Kay and Womble [11] designate such convexity spaces T_1) if and only if \mathcal{B} includes no triple (a, b, a) with $b \neq a$. We will restrict our attention to ternary relations \mathcal{B} such that

$$(a, b, c) \in \mathcal{B} \Rightarrow (c, b, a) \in \mathcal{B} \text{ and } a, b, c \text{ are pairwise distinct;}$$

any such \mathcal{B} will be called a *strict betweenness*.

Theorem 1. *For every strict betweenness \mathcal{B} on a finite ground set E , the following two propositions are logically equivalent:*

- (i) *For all subsets X of E and all x_1, x_2, x_3 in X such that $(x_1, x_2, x_3) \in \mathcal{B}$, there are \bar{x}_1, \bar{x}_3 in $\text{ex}_{\mathcal{B}}(X)$ such that $(\bar{x}_1, x_2, \bar{x}_3) \in \mathcal{B}$.*
- (ii) *$(a, b, c_2), (c_1, c_2, c_3) \in \mathcal{B} \Rightarrow (a, b, c_1) \in \mathcal{B} \text{ or } (a, b, c_3) \in \mathcal{B} \text{ or } (c_1, b, c_3) \in \mathcal{B}$.*

□

Following [11], a convexity space is said to have *Carathéodory number d* if, and only if, d is the smallest positive integer with the following property:

if a point lies in the convex hull of a set X ,
then it lies in the convex hull of a subset X' of X such that $|X'| \leq d$.

Theorem 1 characterizes a class of ternary relations \mathcal{B} on finite ground sets E such that the corresponding class of convexity spaces $(E, \mathcal{N}_{\mathcal{B}})$ consists exclusively of convex geometries with Carathéodory number at most 2. However,

it does not characterize all such relations: for instance, if $E = \{a, b, c_2, c_3\}$ and

$$\mathcal{B} = \{(a, b, c_2), (c_2, b, a), (a, c_2, c_3), ((c_3, c_2, a))\},$$

then $(E, \mathcal{N}_{\mathcal{B}})$ is a convex geometry with Carathéodory number 2 and yet \mathcal{B} does not satisfy the conditions of Theorem 1.

Strict order betweenness [15] in a partially ordered set (E, \preceq) is defined by

$$\mathcal{B} = \{(a, b, c) \in E^3 : a \prec b \prec c \text{ or } c \prec b \prec a\};$$

monophonic [10], or *minimal path* [5], betweenness in an undirected graph with a vertex-set E is defined by

$$\mathcal{B} = \{(a, b, c) \in E^3 : b \text{ is an interior vertex of a chordless path from } a \text{ to } c\}.$$

Strict order betweenness satisfies condition (ii) of Theorem 1: it is a straightforward exercise to verify that it satisfies the stronger condition

$$(a, b, c_2), (c_1, c_2, c_3) \in \mathcal{B} \Rightarrow (a, b, c_1) \in \mathcal{B} \text{ or } (a, b, c_3) \in \mathcal{B}.$$

We shall prove that monophonic betweenness, too, satisfies this stronger condition.

Theorem 2. *Let G be a finite triangulated graph and let a, b, c_1, c_2, c_3 be vertices of G . If*

*b is an interior vertex of a chordless path between a and c_2 and
 c_2 is an interior vertex of a chordless path between c_1 and c_3 ,*

then

*b is an interior vertex of a chordless path between a and c_1 , or else
 b is an interior vertex of a chordless path between a and c_3 .*

□

Theorem 3. *For every strict betweenness \mathcal{B} on a finite ground set E , the following two propositions are logically equivalent:*

- (i) *For all subsets X of E and all x_1, x_2, x_3 in X such that $(x_1, x_2, x_3) \in \mathcal{B}$, there is an \bar{x}_3 in $\text{ex}_{\mathcal{B}}(X)$ such that $(x_1, x_2, \bar{x}_3) \in \mathcal{B}$.*
- (ii) $(a, b, c_2), (c_1, c_2, c_3) \in \mathcal{B} \Rightarrow (a, b, c_1) \in \mathcal{B} \text{ or } (a, b, c_3) \in \mathcal{B}.$

□

3 Proofs

Our proof of Theorem 1 parallels a proof of the theorem of Dietrich [2] that characterizes antimatroids in terms of circuits (see also Theorem 3.9 in Chapter III of [14]). It begins with a pair of auxiliary results.

Lemma 1. *Let \mathcal{B} be a strict betweenness on a finite ground set E . If*

$$(a, b, c_2), (c_1, c_2, c_3) \in \mathcal{B} \Rightarrow (a, b, c_1) \in \mathcal{B} \text{ or } (a, b, c_3) \in \mathcal{B} \text{ or } (c_1, b, c_3) \in \mathcal{B},$$

then, with $\mathcal{N} = \mathcal{N}_{\mathcal{B}}$,

$$\tau_{\mathcal{N}}(X) = X \cup \{b : \text{there are } a, c \text{ in } X \text{ with } (a, b, c) \in \mathcal{B}\}$$

for all subsets X of E .

Proof. Write $X' = \{b : \text{there are } a, c \text{ in } X \text{ with } (a, b, c) \in \mathcal{B}\}$. Since $\tau_{\mathcal{N}}(X)$ is a convex superset of X , it is a superset of $X \cup X'$; our task reduces to proving that $X \cup X'$ is convex. For this purpose, consider an arbitrary b in E such that $(a, b, c) \in \mathcal{B}$ for some a, c in $X \cup X'$: we are going to prove that $b \in X \cup X'$.

CASE 1: $a, c \in X$.

In this case, $b \in X'$ by definition of X' .

CASE 2: $a \in X, c \in X'$.

By definition of X' , there are c_1, c_3 in X with $(c_1, c, c_3) \in \mathcal{B}$; the hypothesis of the lemma with $c_2 = c$ guarantees that $(c_1, b, c_3) \in \mathcal{B}$ or $(a, b, c_1) \in \mathcal{B}$ or $(a, b, c_3) \in \mathcal{B}$. But then we are back in Case 1.

CASE 3: $a, c \in X'$.

As in Case 2, we find c_1, c_3 in X such that $(c_1, b, c_3) \in \mathcal{B}$ or $(a, b, c_1) \in \mathcal{B}$ or $(a, b, c_3) \in \mathcal{B}$. If $(c_1, b, c_3) \in \mathcal{B}$, then we are back in Case 1; if $(a, b, c_1) \in \mathcal{B}$ or $(a, b, c_3) \in \mathcal{B}$, then we are back in Case 2. \square

Lemma 2. *Let \mathcal{B} be a strict betweenness on a finite ground set E . If*

$$(a, b, c_2), (c_1, c_2, c_3) \in \mathcal{B} \Rightarrow (a, b, c_1) \in \mathcal{B} \text{ or } (a, b, c_3) \in \mathcal{B} \text{ or } (c_1, b, c_3) \in \mathcal{B},$$

then $(E, \mathcal{N}_{\mathcal{B}})$ is a convex geometry.

Proof. Write $\mathcal{N} = \mathcal{N}_{\mathcal{B}}$. We will show that the convexity space (E, \mathcal{N}) has the anti-exchange property. For this purpose, assume the contrary: there are a subset X of E and distinct points y, z outside $\tau_{\mathcal{N}}(X)$ such that $y \in$

$\tau_{\mathcal{N}}(X \cup \{z\})$ and $z \in \tau_{\mathcal{N}}(X \cup \{y\})$. Since $y \in \tau_{\mathcal{N}}(X \cup \{z\}) - \tau_{\mathcal{N}}(X)$ and $y \neq z$, Lemma 1 guarantees that $(x_y, y, z) \in \mathcal{B}$ for some x_y in X ; similarly, $(x_z, z, y) \in \mathcal{B}$ for some x_z in X . But then the hypothesis with $a = x_y$, $b = y$, $c_1 = y$, $c_2 = z$, $c_3 = x_z$ implies that $(x_y, y, x_z) \in \mathcal{B}$, and so $y \in \tau_{\mathcal{N}}(X)$, a contradiction. \square

Proof of Theorem 1. To see that (i) implies (ii), set $X = \{a, b, c_1, c_2, c_3\}$ and $x_1 = a$, $x_2 = b$, $x_3 = c_2$ in (i). To show that (ii) implies (i), consider an arbitrary subset X of E and arbitrary x_1, x_2, x_3 in X such that $(x_1, x_2, x_3) \in \mathcal{B}$; let K denote the convex hull of X . Since $x_1, x_2, x_3 \in K$, we have $x_2 \notin \text{ex}_{\mathcal{B}}(K)$, but Lemma 2 guarantees that x_2 belongs to the convex hull of $\text{ex}_{\mathcal{B}}(K)$; now Lemma 1 (with $\text{ex}_{\mathcal{B}}(K)$ in place of X) provides \bar{x}_1, \bar{x}_3 in $\text{ex}_{\mathcal{B}}(K)$ such that $(\bar{x}_1, x_2, \bar{x}_3) \in \mathcal{B}$. Finally, Lemma 1 shows that $\text{ex}_{\mathcal{B}}(K) \subseteq X$, and so $\bar{x}_1, \bar{x}_3 \in \text{ex}_{\mathcal{B}}(X)$. \square

Proof of Theorem 2. Let P_1 denote the chordless path from a to c_2 that passes through b and let P_2 denote the chordless path from c_1 to c_3 that passes through c_2 . Proceeding along P_1 from a to c_2 , we label the vertices consecutively as v_1, v_2, \dots, v_m , so that

$$a = v_1, \quad b = v_s \text{ for some } s \text{ such that } 2 \leq s \leq m-1, \quad c_2 = v_m;$$

proceeding along P_2 from c_1 to c_3 , we label the vertices consecutively as w_1, w_3, \dots, w_n , so that

$$c_1 = w_1, \quad c_2 = w_t \text{ for some } t \text{ such that } 2 \leq t \leq n-1, \quad c_3 = w_n.$$

We claim that

- (\star) none of v_1, v_2, \dots, v_{m-2} has a neighbour w_i with $i < t$ or
 none of v_1, v_2, \dots, v_{m-2} has a neighbour w_j with $j > t$.

To justify this claim, assume the contrary: there are edges $v_k w_i$ and $v_\ell w_j$ with $k, \ell \leq m-2$ and $i < t, j > t$. Choose them so that $|k - \ell|$ is minimized (we may have $k = \ell$) and, subject to this constraint, i is maximized and j is minimized; let P denote the segment of P_1 that stretches between v_k and v_ℓ . Now v_k is the only vertex on P that has a neighbour in $\{w_1, w_2, \dots, w_{t-1}\}$ and v_ℓ is the only vertex on P that has a neighbour in $\{w_{t+1}, w_{t+2}, \dots, w_n\}$; as $w_t = v_m$ and $k, \ell \leq m-2$, no vertex on P is adjacent to w_t or identical with w_t . It follows that the paths P and $w_i w_{i+1} \dots w_j$ are vertex-disjoint and

that their union induces a chordless cycle through at least four vertices; this contradiction completes the proof of (\star) .

After flipping P_2 if necessary, (\star) lets us assume that none of v_1, v_2, \dots, v_{s-1} has a neighbour w_i with $i < t$. Since the walk $v_s v_{s+1} \dots v_m w_{t-1} \dots w_2 w_1$ connects b to c_1 , some subset of its vertices induces a chordless path P from b to c_1 ; now b is an interior vertex of the chordless path $v_1 v_2 \dots v_{s-1} P$ between a and c_1 . \square

Proof of Theorem 3. To see that (i) implies (ii), set $X = \{a, b, c_1, c_2, c_3\}$ and $x_1 = a, x_2 = b, x_3 = c_2$ in (i). To show that (ii) implies (i), we shall use induction on $|X|$. If $|X| \leq 2$, then the conclusion is vacuously true. For the induction step, consider arbitrary x_1, x_2, x_3 in X such that $(x_1, x_2, x_3) \in \mathcal{B}$. Setting

$$Z = \{z \in X : (x_1, x_2, z) \in \mathcal{B}\},$$

we shall proceed to prove that $Z \cap \text{ex}_{\mathcal{B}}(X) \neq \emptyset$.

First we claim that, with \mathcal{N} a shorthand for $\mathcal{N}_{\mathcal{B}}$ as usual,

- $\tau_{\mathcal{N}}(X - Z) \cap Z = \emptyset$.

To justify this claim, assume the contrary: there is a triple (c_1, c_2, c_3) in \mathcal{B} such that $c_1 \in X - Z, c_2 \in Z, c_3 \in X - Z$. But then the hypothesis of the theorem is contradicted by $a = x_1, b = x_2$.

Next, let us write $z' \prec z''$ if and only if $z', z'' \in Z$ and there exists a y in $X - Z$ such that $(y, z', z'') \in \mathcal{B}$; note that $z' \prec z'' \Rightarrow z' \neq z''$. We claim that

- \prec is antisymmetric.

To justify this claim, assume the contrary: there are z_1, z_2 in Z with $z_1 \prec z_2, z_2 \prec z_1$. By definition, there are y_1, y_2 in $X - Z$ such that $(y_1, z_1, z_2) \in \mathcal{B}$ and $(y_2, z_2, z_1) \in \mathcal{B}$. But then the hypothesis of the theorem is contradicted by $a = y_1, b = z_1, c_1 = y_2, c_2 = z_2, c_3 = z_1$: since $\tau_{\mathcal{N}}(X - Z) \cap Z = \emptyset$, we have $(y_1, z_1, y_2) \notin \mathcal{B}$.

In addition, we claim that

- \prec is transitive.

To justify this claim, consider any z_1, z_2, z_3 in Z such that $z_1 \prec z_2$ and $z_2 \prec z_3$. By definition, there are y_1, y_2 in $X - Z$ such that $(y_1, z_1, z_2), (y_2, z_2, z_3) \in \mathcal{B}$; as $\tau_{\mathcal{N}}(X - Z) \cap Z = \emptyset$ guarantees that $(y_1, z_1, y_2) \notin \mathcal{B}$, the hypothesis of the

theorem with $a = y_1$, $b = z_1$, $c_1 = y_2$, $c_2 = z_2$, $c_3 = z_3$ implies $(y_1, z_1, z_3) \in \mathcal{B}$, and so $z_1 \prec z_3$.

Our set Z is nonempty (it includes x_3) and it is partially ordered by \prec . Let Z_{\max} denote the set of its maximal elements. We claim that

- $Z_{\max} \cap \text{ex}_{\mathcal{B}}(Z) \subseteq \text{ex}_{\mathcal{B}}(X)$.

To justify this claim, assume the contrary: there are a, z_2, c in X such that $z_2 \in Z_{\max} \cap \text{ex}_{\mathcal{B}}(Z)$ and $(a, z_2, c) \in \mathcal{B}$. Since $\tau_{\mathcal{N}}(X - Z) \cap Z = \emptyset$, at least one of a, c belongs to Z ; since $z_2 \in \text{ex}_{\mathcal{B}}(Z)$, at most one of a, c belongs to Z ; now symmetry allows us to assume that $a \in X - Z$ and $c \in Z$. But then $z_2 \prec c$, contradicting the assumption that $z_2 \in Z_{\max}$.

We shall complete the proof by showing that

- $Z_{\max} \cap \text{ex}_{\mathcal{B}}(Z) \neq \emptyset$.

For this purpose, we rely on the induction hypothesis; note that $|Z| < |X|$ as Z includes neither x_1 nor x_2 .

CASE 1: $Z_{\max} \neq Z$.

In this case, let z be any maximal element of $Z - Z_{\max}$. Since $z \notin Z_{\max}$, there are a y in $X - Z$ and a z_2 in Z_{\max} such that $(y, z, z_2) \in \mathcal{B}$. If $z_2 \in \text{ex}_{\mathcal{B}}(Z)$, then we are done; else there are elements z_1, z_3 of Z such that $(z_1, z_2, z_3) \in \mathcal{B}$. Now the induction hypothesis applied to Z and (z_1, z_2, z_3) yields a \bar{z}_3 in $\text{ex}_{\mathcal{B}}(Z)$ such that $(z_1, z_2, \bar{z}_3) \in \mathcal{B}$; next, the induction hypothesis applied to Z and (\bar{z}_3, z_2, z_1) yields a \bar{z}_1 in $\text{ex}_{\mathcal{B}}(Z)$ such that $(\bar{z}_3, z_2, \bar{z}_1) \in \mathcal{B}$. The hypothesis of the theorem with $a = y, b = z, c_1 = \bar{z}_1, c_2 = z_2, c_3 = \bar{z}_3$ guarantees that a subscript i in $\{1, 3\}$ satisfies $z \prec \bar{z}_i$; now maximality of z implies $\bar{z}_i \in Z_{\max}$.

CASE 2: $Z_{\max} = Z$.

In this case, our task reduces to proving that $\text{ex}_{\mathcal{B}}(Z) \neq \emptyset$. We may assume that $\text{ex}_{\mathcal{B}}(Z) \neq Z$ (else we are done), and so \mathcal{B} includes a triple (z_1, z_2, z_3) such that z_1, z_2, z_3 are elements of Z . But then the induction hypothesis applied to Z and (z_1, z_2, z_3) yields a \bar{z}_3 in $\text{ex}_{\mathcal{B}}(Z)$. \square

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