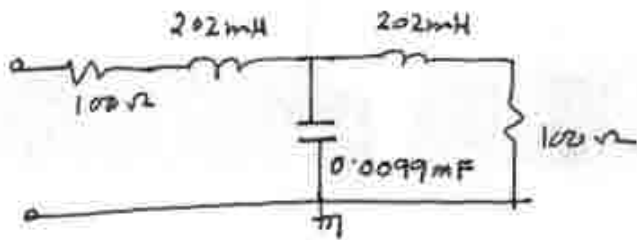


Q2 (A4) U6 class only

ELEC441, MT2
W0809

PS/11

The frequency denormalized and impedance scaled LC, R ladder filter is:



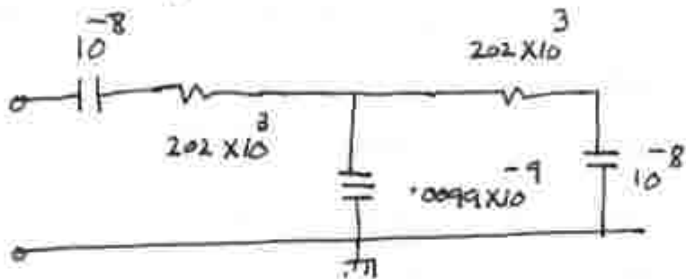
For FDNR technique we consider an impedance scaling by $\frac{1}{R\Delta}$. So

$$R \rightarrow \frac{R}{R\Delta} = \frac{1}{\Delta \left(\frac{R}{R}\right)} = \frac{1}{\Delta C} ; \bar{C} = \frac{R}{R}$$

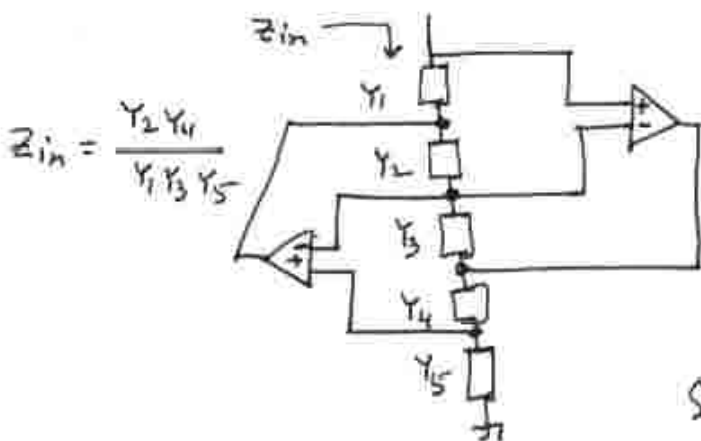
$$L \rightarrow \Delta L / R\Delta = \frac{L}{R} = \bar{R} ; \bar{R} = \frac{L}{R}$$

$$C \rightarrow \frac{1}{\Delta C} \frac{1}{R\Delta} = \frac{1}{\Delta^2} \cdot \frac{1}{RC} = -\frac{1}{\omega^2} \cdot \frac{1}{D} ; D = RC$$

The new filter will then look like: let $R = 10^{-6}$



For the super capacitor D, we use the GIC circuit



$$Z_{in} = \frac{Y_2 Y_4}{Y_1 Y_3 Y_5}$$

with $Y_2, Y_4, Y_5 \rightarrow \frac{1}{sC} G_x$ each

and $Y_1, Y_3 \rightarrow \frac{1}{sC} G_x$ each

$$Z_{in} = \frac{1}{s^2 C^2} \frac{D}{G_x}$$

$$= -\frac{1}{\omega^2} \frac{1}{C} \cdot G_x$$

$$\text{So } D = RC = \frac{G_x}{G_x}$$

Q2 (alt.)
 → Utk class only

But here $D = 0.0099 \times 10^{-9} = \frac{1}{\omega^2 C_x^2 R_x}$

Let $G_x \rightarrow \frac{1}{R_x} = 10^{-2}$ i.e. $R_x = 100 \Omega$

Then $\frac{1}{C_x} = 0.0099 \times 10^{-9} \times 10^{-6} = 0.0099 \times 10^{-15}$

p6/11

But here $D = 0.0099 \times 10^{-9} = \frac{15k}{C_x} \frac{C_x}{G_x}$

$C_x \approx G_x \times 99 \times 10^{-13}$

If $G_x = 10^{-2}$, i.e. $R_2, R_3, R_4 = 100 \Omega$ each

$C_x = 99 \times 10^{-15} = 99 \text{ f} = 0.099 \text{ pF}$

Q2:
 Alt.

With $Y_2, Y_4, Y_3 = G_x$, $Y_1, Y_5 \rightarrow \mu C_x$ each

$Z_{in} = \frac{G_x}{s^2 C_x^2} = -\frac{1}{\omega^2 C_x^2} G_x$; So $D = \frac{C_x^2}{G_x}$

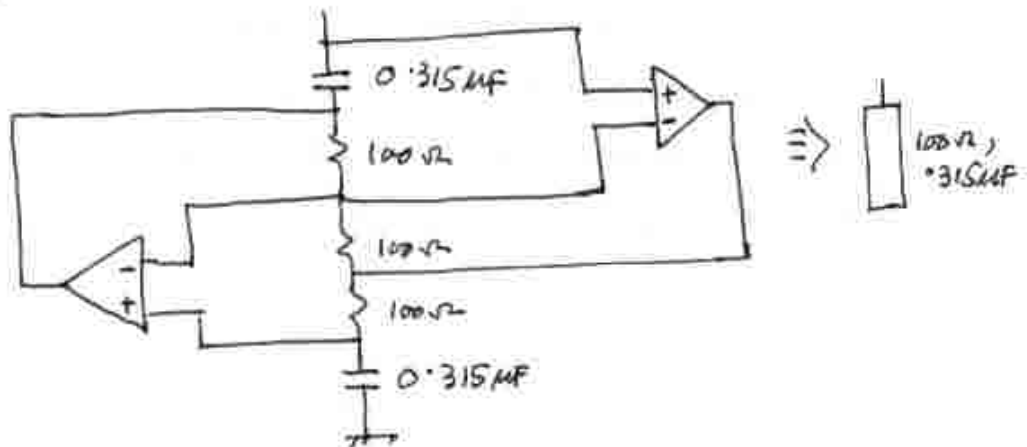
But here, $D = 0.0099 \times 10^{-9} = \frac{C_x^2}{G_x}$

Let $G_x = 10^{-2}$ i.e. $R_2 = R_4 = R_3 = 100 \Omega$

So $C_x^2 = 0.0099 \times 10^{-11} = 99 \times 10^{-15}$

$C_x = \sqrt{99 \times 10^{-15}} = 0.315 \times 10^{-6}$

So design for D is:

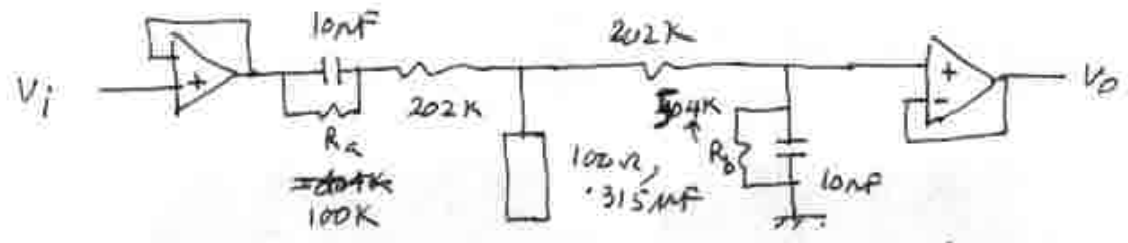


Q2
Alt.

U4 class only

P7/11

The overall complete system will include buffers at input and output, together with resistive paths through the filter structure. Thus:



DC gain of the designed network is:

$$\frac{R_b}{R_b + R_a + 404K} = \text{DC gain of original ladder filter} = 0.5$$

$$R_b = 0.5 R_a + 202K ; \quad \text{if } R_a = R_b = 202K$$

$$R = 404K \quad R_b = R_a + 404K ; \quad \text{let } R_a = 100K, \text{ then } R_b = 504K$$

This completes the system design.

$$\left\langle \frac{504K}{100K + 404K + 504K} \rightarrow 0.5 \text{ DC gain.} \right\rangle$$

Q3:
Q2:

ps/11

$$T_N(s) = \frac{s^2 + 1}{s^2 + 1.5s + 1}$$

One can frequency denormalize by $\omega_0 = \sqrt{\omega_c \omega_h} = 2000$ rad/sec.
or, one can design the filter for

$$T_N = \frac{s^2 + 1}{s^2 + 1.5s + 1} \text{ and}$$

then use frequency denormalization.

After frequency denormalization, one gets

$$T(s) = \frac{\frac{s^2}{\omega_0^2} + 1}{\frac{s^2}{\omega_0^2} + 1.5 \frac{s}{\omega_0} + 1} = \frac{s^2 + \omega_0^2}{s^2 + 1.5s\omega_0 + \omega_0^2}$$

Example designing state variable technique { Possible Design #1 }

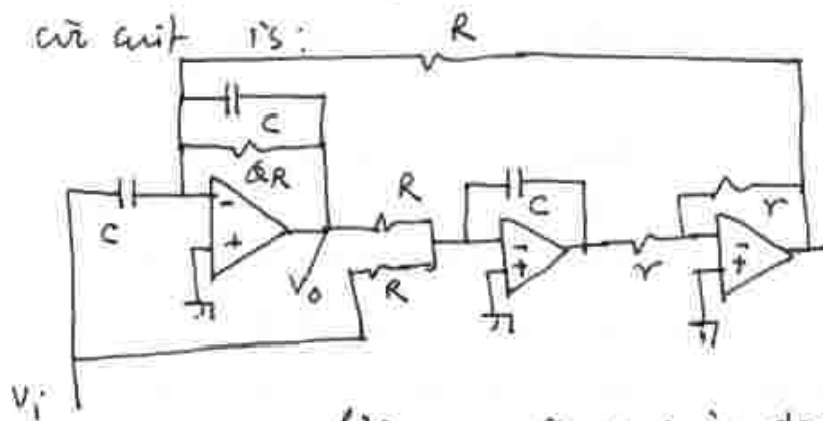
Tow-Thomas biquad

For $T_N(s)$, we see $T_N(s)|_{s \rightarrow \infty} = 1$; $\omega_n^2 = \omega_p^2 = 1$

So $C_1 = C$; $R_1 = \text{open}$ (does not exist)

$$R_2 = R \cdot \left(\frac{\omega_p}{\omega_n}\right)^2 \cdot \frac{1}{\text{hf gain}} = R \quad \because \omega_p = \omega_n \text{ here. hf gain} = 1$$

The circuit is:

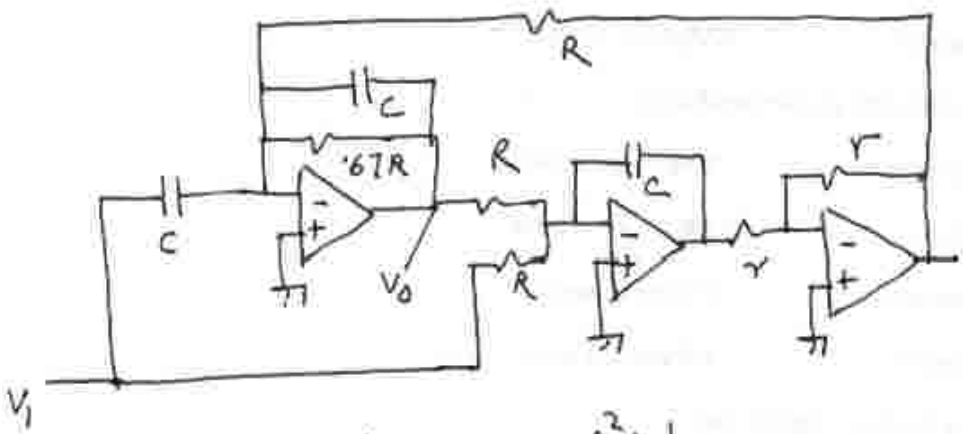


$$\frac{\omega_p}{\omega_n} = \text{coeff. of } s \text{ in denom.} = 1.5, \text{ while } \omega_p^2 = 1$$

$$Q = \frac{\omega_p}{1.5} = \frac{1}{1.5} = 0.67$$

Q3:
Q1 (contd.)

Thus the circuit is:



$$T_N(s) = \frac{V_0}{V_i} = \frac{s^2 + 1}{s^2 + 1.5s + 1}$$

For normalized filter we take $R=1, r=1, C=1$.

For frequency denormalized filter, $\therefore \omega_p = 2000 \text{ rad/sec}$,
we can take $R = \frac{1}{\sqrt{2000}}$ & $C = \frac{1}{\sqrt{2000}}$, so

that $\frac{1}{RC}$ becomes 2000. ~~we can keep~~

Thus $R = 2.236 \times 10^{-2}$; $C = 2.236 \times 10^{-2}$

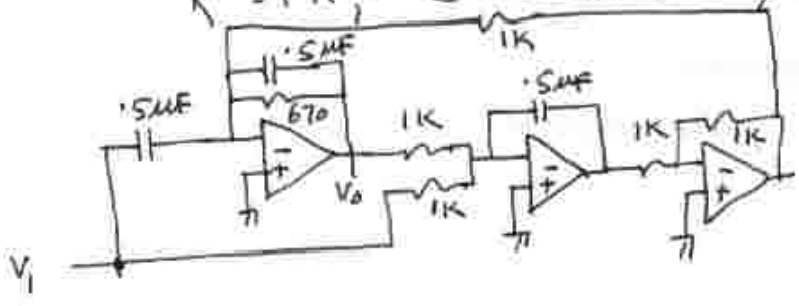
For practical $R = 1 \text{ k}$, we use impedance

scaling by $\frac{1000}{2.236 \times 10^{-2}} = 44721.36$

Then $R = 1 \text{ k}$; $C = \frac{2.236 \times 10^{-2}}{44721.36} = 0.499 \mu\text{F}$

Let $r = 1 \text{ k}$ also. So final design is:

$R = 1 \text{ k}$; $C = 0.5 \mu\text{F}$; $r = 1 \text{ k}$



Q3: (Contd.) Using Fleischer-Tow circuit

Possible Design #2

P10/11

$$\frac{V_o}{V_i} = - \frac{\left(\frac{R_3}{R_6}\right) s^2 + \frac{1}{R_1 C_1} \left[\frac{R_3}{R_6} - \frac{R_1 R_8}{R_4 R_7} \right] s + \frac{R_8}{R_3 R_5 R_7 C_1 C_2}}{s^2 + \frac{1}{R_1 C_1} s + \frac{R_8}{R_2 R_3 C_1 C_2 R_7}}$$

To match with

$$|T_N| = \frac{s^2 + 1}{s^2 + 1.5s + 1}$$

We shall make $\frac{R_3}{R_6} = 1$; $\frac{R_8}{R_3 R_5 R_7 C_1 C_2} = 1$

$$\frac{R_3}{R_6} = \frac{R_1 R_8}{R_4 R_7} \quad \& \quad \frac{1}{C_1 R_1} = 1.5; \quad \frac{R_8}{R_2 R_3 C_1 C_2 R_7} = 1$$

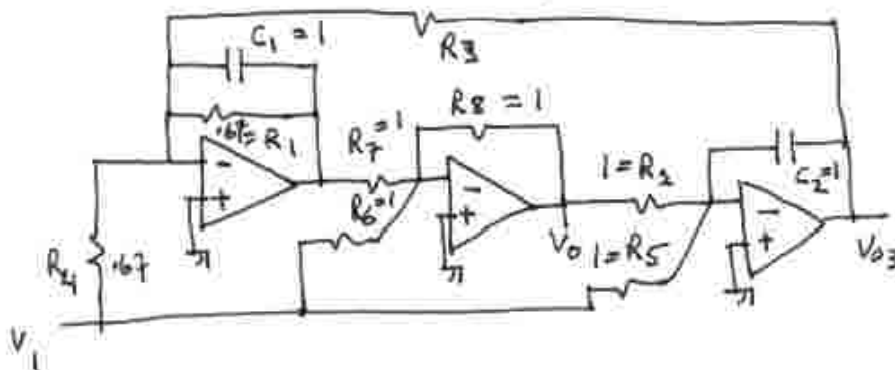
Let $R_3 = 1 = R_6 = R_5 = R_7 = C_1 = C_2 = R_2$

Then $\frac{1}{C_1 R_1} \Rightarrow \frac{1}{R_1} = 1.5$; $R_1 = 0.67$

$$\frac{1}{R_2} = 1; \quad R_2 = 1.$$

$$\frac{R_1 R_8}{R_4 R_7} = \frac{0.67 \cdot 1}{R_4 \cdot 1} = \frac{R_8}{R_6} = 1 \quad \therefore R_4 = 0.67 = R_1$$

Thus, the normalized design circuit is:



For frequency denormalized filter, since

Q3:

$$\frac{R_8}{R_3 R_5 R_7 C_1 C_2} = \omega_0^2 = \frac{R_8}{R_2 R_3 C_1 C_2 R_7}$$

P11/11

We can make $C_1 = C_2 = \frac{1}{\omega_0} = \frac{1}{2000}$

Second cut design is:

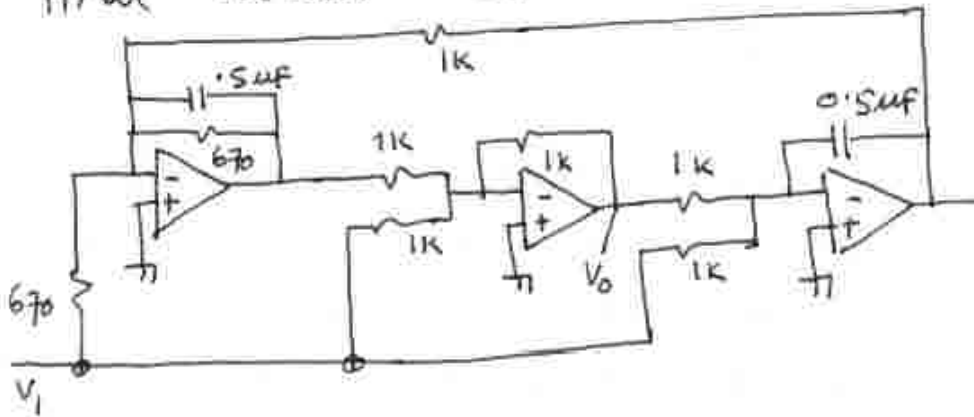
$C_1 = C_2 = 0.0005 \text{ F}$, all others as before.

If now we want $R_8 = R_3 = R_5 = R_7 = 1 \text{ k}\Omega$
we do impedance scaling. Then

$C_1 = C_2 = 0.0005 / 1000 = 5 \times 10^{-7} = 0.5 \mu\text{F}$

$R_1 = R_4 = 670 \Omega$, other resistances = $1 \text{ k}\Omega$.

Final circuit is:



X

~~Q1:~~
Q1:

By inspection

ELEC 441/6081 M72 } \Rightarrow 1/11
W0809

OA1 receiver input at phase 1. So

$$V_1^{(1)} = -\frac{1}{D} \cdot V_i^{(1)} \cdot G \cdot \frac{1}{1-z^{-1}} + \frac{1}{D} \cdot V_i^{(2)} \cdot H \cdot \frac{z^{-1/2}}{1-z^{-1}} - \frac{1}{D} \cdot V_2^{(1)} \cdot C \cdot \frac{1}{1-z^{-1}}$$
$$= -\frac{G}{D} \cdot \frac{1}{1-z^{-1}} V_i^{(1)} + \frac{H}{D} \cdot \frac{z^{-1/2}}{1-z^{-1}} V_i^{(2)} - \frac{C}{D} \cdot \frac{1}{1-z^{-1}} V_2^{(1)}$$

Using $V_i^{(2)} = z^{-1/2} V_i^{(1)}$

$$V_1^{(1)} = -\frac{G}{D} \cdot \frac{1}{1-z^{-1}} V_i^{(1)} + \frac{H}{D} \cdot \frac{z^{-1}}{1-z^{-1}} V_i^{(1)} - \frac{C}{D} \cdot \frac{1}{1-z^{-1}} V_2^{(1)}$$

For OA2, similarly,

$$V_2^{(1)} = -\frac{F}{B} \cdot \frac{1}{1-z^{-1}} V_2^{(1)} + \frac{A}{B} \cdot \frac{z^{-1/2}}{1-z^{-1}} V_1^{(2)}$$

Using $V_1^{(2)} = z^{-1/2} V_1^{(1)}$

$$V_2^{(1)} = -\frac{F}{B} \cdot \frac{1}{1-z^{-1}} V_2^{(1)} + \frac{A}{B} \cdot \frac{z^{-1}}{1-z^{-1}} V_1^{(1)}$$

Changing sides

$$V_2^{(1)} \left[1 + \frac{F}{B} \cdot \frac{1}{1-z^{-1}} \right] = \frac{A}{B} \cdot \frac{z^{-1}}{1-z^{-1}} V_1^{(1)}$$

$$V_2^{(1)} \left[1 + \frac{F}{B} \cdot \frac{1}{1-z^{-1}} \right] = \frac{A}{B} \cdot \frac{z^{-1}}{1-z^{-1}} \left[\left(-\frac{G}{D} + \frac{H}{B} z^{-1} \right) \frac{1}{1-z^{-1}} V_i^{(1)} - \frac{C}{D} \frac{1}{(1-z^{-1})} V_2^{(1)} \right]$$

$$\therefore V_2^{(1)} \left[1 + \frac{F}{B} \cdot \frac{1}{1-z^{-1}} + \frac{AC}{BD} \cdot \frac{z^{-1}}{(1-z^{-1})^2} \right] = \frac{A}{B} \cdot \frac{z^{-1}}{(1-z^{-1})^2} \left(-\frac{G}{D} + \frac{H}{B} z^{-1} \right) V_i^{(1)}$$

$$V_2^{(1)} \frac{[BD(1-z^{-1})^2 + FD(1-z^{-1}) + ACz^{-1}]}{BD(1-z^{-1})^2} = \frac{A}{B} \cdot \frac{1}{(1-z^{-1})^2} \left(-\frac{G}{D} z^{-1} + \frac{H}{B} z^{-2} \right) V_i^{(1)}$$

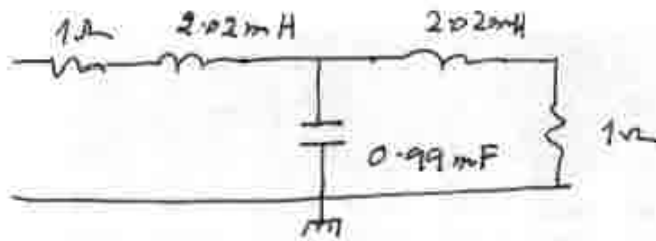
~~Q1:~~ $V_2^{(1)} [BD(1-z^{-1})^2 + ED(1-z^{-1}) + ACz^{-1}]$
 $= AD \left[-\frac{G}{D} z^{-1} + \frac{H}{D} z^{-2} \right] V_1^{(1)}$

$$\frac{V_2^{(1)}}{V_1^{(1)}} = \frac{AH z^{-2} - GA z^{-1}}{BD(1-z^{-1})^2 + ED(1-z^{-1}) + ACz^{-1}}$$

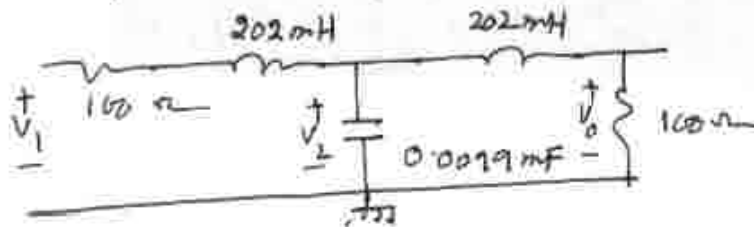
Q.2

The frequency denormalized filter is:

p3/11



The impedance & frequency denormalized filter is:



For operational simulation:

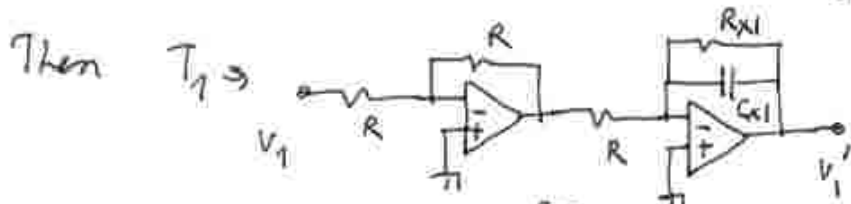
$$Y_1 \rightarrow \frac{100 \Omega \quad 202 \text{mH}}{\quad} \rightarrow \frac{1}{100 + s \times 202 \times 10^{-3}} = \frac{1}{202 \times 10^{-3}} \cdot \frac{1}{s + \frac{100}{202 \times 10^{-3}}}$$

$$T_1 = R Y_1 = \frac{R / 202 \times 10^{-3}}{s + \frac{100}{202 \times 10^{-3}}}$$

$$-Z_2 = -\frac{1}{s \times 0.0099 \text{mF}} = -\frac{1}{s \times 9.9 \times 10^{-7}} = -\frac{1}{s \times 9.9 \times 10^{-6}}$$

$$-T_2 = -\frac{Z_2}{R} = -\frac{1}{s \times R \times 9.9 \times 10^{-6}}$$

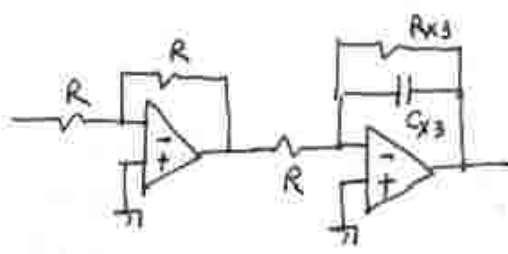
$$Y_3 \frac{202 \text{mH} \quad 100 \Omega}{\quad} \rightarrow T_3 = \frac{R / 202 \times 10^{-3}}{s + \frac{100}{202 \times 10^{-3}}}$$



Q202
Control

For T_3 :

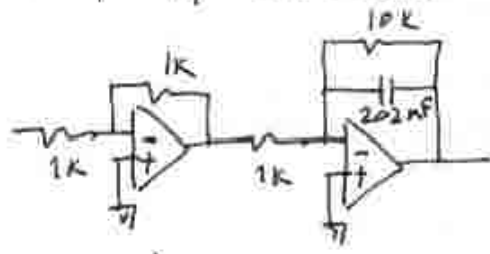
P4/11



Let $R = 1k\Omega$

The design equations are: $R_x = \frac{R^2}{R_c} \quad \& \quad C_x = \frac{L}{R^2}$

Thus for T_1 we have

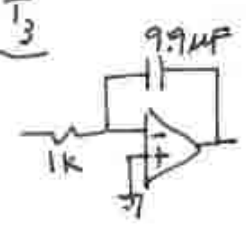


$$R_x = \frac{10^6}{100} = 10^4 = 10k$$

$$C_x = \frac{L}{R^2} = \frac{202mH}{10^6} = 202nF$$

So also for T_3

For $T_2 \Rightarrow$



$$\frac{1}{RC_x2} \Rightarrow \frac{1}{RC} \quad C_{x2} = C = 9.9\mu F$$

The interconnection is:

