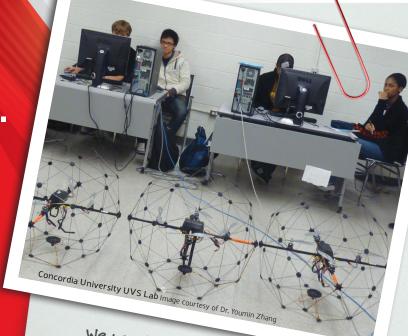
Unmanned vehicles. Let students take control.

The Quanser Unmanned Vehicle Systems (UVS) Laboratory is a multi-purpose, multi-agent platform for study and development of unmanned aerial vehicles and mobile robotics. Designed for indoor use, with this lab you can perform a wide range of experiments, including vehicle modeling and control, motion planning, obstacle avoidance, sensor fusion, fleet maintenance, multi-agent navigation and autonomous/supervisory operation in a safe, controlled environment.



We use Qballs in our courses for undergraduate and graduate of flight control. This cutting-edge with engineering practice. Students continue in their studies and work.

Dr. Youmin Zhang Concordia University, Canada

Six components of an unmanned vehicle lab:



PC-based control station optimizes UVS Labs. PC is pre-configured with MATLAB®/Simulink®, Real-Time Workshop®, QUARC® control design software and pre-designed controller.



Qball-X4 unmanned aerial vehicle, an openarchitecture quadrotor with an embedded computer is ideal for advanced multi-agent missions and teaching basic vehicle navigation and control.



Qbot mobile robot has a built-in processor, sensors and vision system. Curriculum is included and gives students hands-on experience with motion planning, mapping, path tracking, obstacle avoidance and more.



Onboard data acquisition and computer allow for wireless communication between unmanned vehicles. Configure parameters in real-time and observe sensor measurements from control station.



Tracking system consists of six infrared cameras that allow for accurate measurement of unmanned vehicle positions, essential for performing autonomous missions.



QUARC® control design software integrates with Simulink® and allows students to design, implement and test control theory in real-time – quickening development and integration.



Inquire about a demo: info@quanser.com or 1-877-781-6737

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