Chapter 9 Random Processes

ENCS6161 - Probability and Stochastic Processes

Concordia University

Definition of a Random Process

- Assume the we have a random experiment with outcomes w belonging to the sample set S. To each $w \in S$, we assign a time function X(t,w), $t \in I$, where I is a time index set: discrete or continuous. X(t,w) is called a random process.
- If w is fixed, X(t,w) is a deterministic time function, and is called a realization, a sample path, or a sample function of the random process.
- If $t = t_0$ is fixed, $X(t_0, w)$ as a function of w, is a random variable.
- A random process is also called a stochastic process.

Definition of a Random Process

• Example: A random experment has two outcomes $w \in \{0, 1\}$. If we assign:

$$X(t,0) = A\cos t$$

$$X(t,1) = A \sin t$$

where A is a constant. Then X(t,w) is a random process.

• Usually we drop w and write the random process as X(t).

Joint distribution of time samples Let X_1, \dots, X_n be the samples of X(t, w) obtained at t_1, \dots, t_n , i.e. $X_i = X(t_i, w)$, then we can use the joint CDF

 $F_{X_1\cdots X_n}(x_1,\cdots,x_n)=P[X_1\leq x_1,\cdots,X_n\leq x_n]$ or the joint pdf $f_{X_1\cdots X_n}(x_1,\cdots,x_n)$ to describe a random process partially.

Mean function:

$$m_X(t) = E[X(t)] = \int_{-\infty}^{\infty} x f_{X(t)}(x) dx$$

Autocorrelation function

$$R_X(t_1, t_2) = E[X(t_1)X(t_2)] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{X(t_1)X(t_2)}(x, y) dx dy$$

Autocovariance function

$$C_X(t_1, t_2) = E[(X(t_1) - m_X(t_1))(X(t_2) - m_X(t_2))]$$

= $R_X(t_1, t_2) - m_X(t_1)m_X(t_2)$

a special case:

$$C_X(t,t) = E[(X(t) - m_X(t))^2] = Var[X(t)]$$

The correlation coefficient

$$\rho_X(t_1, t_2) = \frac{C_X(t_1, t_2)}{\sqrt{C_X(t_1, t_1)C_X(t_2, t_2)}}$$

Mean and autocorrelation functions provide a partial description of a random process. Only in certain cases (Gaussian), they can provide a fully description.

• Example: $X(t) = A\cos(2\pi t)$, where A is a random variable.

$$m_X(t) = E[A\cos(2\pi t)] = E[A]\cos(2\pi t)$$

$$R_X(t_1, t_2) = E[A\cos(2\pi t_1) \cdot A\cos(2\pi t_2)]$$

$$= E[A^2]\cos(2\pi t_1)\cos(2\pi t_2)$$

$$C_X(t_1, t_2) = R_X(t_1, t_2) - m_X(t_1)m_X(t_2)$$

$$= (E[A^2] - E[A]^2)\cos(2\pi t_1)\cos(2\pi t_2)$$

$$= Var(A)\cos(2\pi t_1)\cos(2\pi t_2)$$

• Example: $X(t) = A\cos(wt + \Theta)$, where Θ is uniform in $[0, 2\pi]$, A and w are constants.

$$m_X(t) = E[A\cos(wt + \Theta)]$$

$$= \frac{1}{2\pi} \int_0^{2\pi} A\cos(wt + \theta)d\theta = 0$$

$$C_X(t_1, t_2) = R_X(t_1, t_2) = A^2 E[\cos(wt_1 + \Theta)\cos(wt_2 + \Theta)]$$

$$= \frac{A^2}{2\pi} \int_0^{2\pi} \frac{\cos w(t_1 - t_2) + \cos[w(t_1 + t_2) + \theta]}{2} d\theta$$

$$= \frac{A^2}{2} \cos w(t_1 - t_2)$$

Gaussian Random Processes

• A random process X(t) is a Gaussian random process if for any n, the samples taken at t_1, t_2, \dots, t_n are jointly Gaussian, i.e. if

$$X_1 = X(t_1), \cdots, X_n = X(t_n)$$

then

$$f_{X_1...X_n}(x_1, \cdots, x_n) = \frac{e^{-\frac{1}{2}(\underline{x} - \underline{m})^T K^{-1}(\underline{x} - \underline{m})}}{(2\pi)^{n/2} |K|^{1/2}}$$

where $\underline{m} = [m_X(t_1), \cdots, m_X(t_n)]^T$ and

$$K = \begin{bmatrix} C_X(t_1, t_1) & \cdots & C_X(t_1, t_n) \\ \cdots & \cdots & \cdots \\ C_X(t_n, t_1) & \cdots & C_X(t_n, t_n) \end{bmatrix}$$

Multiple Random Processes

- To specify joint random processes X(t) and Y(t), we need to have the pdf of all samples of X(t) and Y(t) such as $X(t_1), \dots, X(t_i), Y(t_1), \dots, Y(t_j)$ for all i and j and all choices of $t_1, \dots, t_i, t_1, \dots, t_j$.
- The processes X(t) and Y(t) are indepedent if the random vectors $(X(t_1), \cdots, X(t_i))$ and $(Y(t_1'), \cdots, Y(t_j'))$ are independent for all i, j and $t_1, \cdots, t_i, t_1', \cdots, t_j'$.

Multiple Random Processes

• The cross-correlation $R_{X,Y}(t_1,t_2)$ is defined as

$$R_{X,Y}(t_1, t_2) = E[X(t_1)Y(t_2)]$$

Two processes are orthogonal if

$$R_{X,Y}(t_1,t_2)=0$$
 for all t_1 and t_2

The cross-covariance

$$C_{X,Y}(t_1, t_2) = E[(X(t_1) - m_X(t_1))(Y(t_2) - m_Y(t_2))]$$

= $R_{X,Y}(t_1, t_2) - m_X(t_1)m_Y(t_2)$

X(t) and Y(t) are uncorrelated if

$$C_{X,Y}(t_1,t_2)=0$$
 for all t_1 and t_2

Multiple Random Processes

• Example: $X(t) = \cos(wt + \Theta)$ and $Y(t) = \sin(wt + \Theta)$, where Θ is uniform in $[0, 2\pi]$ and w is a constant.

$$m_X(t) = m_Y(t) = 0$$

$$C_{X,Y}(t_1, t_2) = R_{X,Y}(t_1, t_2)$$

$$= E[\cos(wt_1 + \Theta)\sin(wt_2 + \Theta)]$$

$$= E\left[-\frac{1}{2}\sin w(t_1 - t_2) + \frac{1}{2}\sin(w(t_1 + t_2) + 2\Theta)\right]$$

$$= -\frac{1}{2}\sin w(t_1 - t_2)$$

Discrete-Time Random Processes

• i.i.d random processes: $X_n \sim f_X(x_n)$ then

$$F_{X_1 \cdots X_n}(x1, \cdots, x_n) = F_X(x1) \cdots F_X(x_n)$$

$$m_X(n) = E[X_n] = m \quad \text{for all } n$$

$$C_X(n_1, n_2) = E[(X_{n_1} - m)(X_{n_2} - m)]$$

$$= E[X_{n_1} - m]E[X_{n_2} - m] = 0 \text{ if } n_1 \neq n_2$$

$$C_X(n, n) = E[(X_n - m)^2] = \sigma^2$$

$$\Rightarrow C_X(n_1, n_2) = \sigma^2 \delta_{n_1, n_2}$$

$$R_X(n_1, n_2) = \sigma^2 \delta_{n_1, n_2} + m^2$$

Discrete-Time Random Processes

Example: let X_n be a sequence of i.i.d. Bernoulli r.v.s. with $P(X_i = 1) = p$.

$$m_X(n) = p$$

 $Var(X_n) = p(1-p)$
 $C_X(n_1, n_2) = p(1-p)\delta_{n_1, n_2}$
 $R_X(n_1, n_2) = p(1-p)\delta_{n_1, n_2} + p^2$

Example:

 $Y_n = 2X_n - 1$, where X_n are i.i.d. Bernoulli r.v.s

$$Y_n = \begin{cases} 1 & \text{with } p \\ -1 & \text{with } (1-p) \end{cases}$$

$$\Rightarrow m_Y(n) = 2p - 1, \ Var(Y_n) = 4p(1-p)$$

Random Walk

- Let $S_n = Y_1 + \cdots + Y_n$, where Y_n are i.i.d. r.v.s. with $P\{Y_n = 1\} = p$ and $P\{Y_n = -1\} = 1 p$. This is a one-dimensional <u>random walk.</u>
- If there are k positive jumps (+1's) in n trials (n walks), then there are n-k negative jumps (-1's). So $S_n=k\times 1+(n-k)\times (-1)=2k-n$ and $P\left\{S_n=2k-n\right\}=\binom{n}{k}p^k(1-p)^{n-k},\quad k=0,1,\cdots,n$

Independent increment

Let $I_1=(n_0,n_1]$ and $I_2=(n_2,n_3]$. If $n_1 \le n_2$, I_2 and I_2 do not overlap. Then the increments on the two intervals are

$$S_{n_1} - S_{n_0} = Y_{n_0+1} + \dots + Y_{n_1}$$

$$S_{n_3} - S_{n_2} = Y_{n_2+1} + \dots + Y_{n_3}$$

Since they have no Y_n 's in common (no overlapping) and Y_n 's are independent.

 $\Rightarrow S_{n_1} - S_{n_0}$ and $S_{n_3} - S_{n_2}$ are independent.

This property is called independent increment.

Stationary increment

Furthermore, if I_1 and I_2 have the same length, i.e $n_1 - n_0 = n_3 - n_2 = m$, then the increments $S_{n_1} - S_{n_0}$ and $S_{n_3} - S_{n_2}$ have the same distribution since they both are the sum of m i.i.d r.v.s This means that the increments over interval of the

This means that the increments over interval of the same length have the same distribution. The process S_n is said to have stationary increment.

 $lue{}$ These two properties can be used to find the joint pmf of S_n

at
$$n_1, \cdots, n_k$$

$$P[S_{n_1} = s_1, S_{n_2} = s_2, \cdots, S_{n_k} = s_k]$$

$$= P[S_{n_1} = s_1, S_{n_2} - S_{n_1} = s_2 - s_1, \cdots, S_{n_k} - S_{n_{k-1}} = s_k - s_{k-1}]$$

$$= P[S_{n_1} = s_1]P[S_{n_2} - S_{n_1} = s_2 - s_1] \cdots P[S_{n_k} - S_{n_{k-1}} = s_k - s_{k-1}]$$
 (from independent increment)
$$= P[S_{n_1} = s_1]P[S_{n_2-n_1} = s_2 - s_1] \cdots P[S_{n_k-n_{k-1}} = s_k - s_{k-1}]$$
 (from stationary increment)

• If Y_n are continuous valued r.v.s.

$$\begin{split} f_{S_{n_1}\cdots S_{n_k}}(s_1,\cdots s_k) \\ &= f_{S_{n_1}}(s_1)f_{S_{n_2-n_1}}(s_2-s_1)\cdots f_{S_{n_k-n_{k-1}}}(s_k-s_{k-1}) \\ \text{e.g., if } Y_n \sim N(0,\sigma^2) \text{ then} \\ f_{S_{n_1},S_{n_2}}(s_1,s_2) &= f_{S_{n_1}}(s_1)f_{S_{n_2-n_1}}(s_2-s_1) \\ &= \frac{1}{\sqrt{2\pi n_1}\sigma}e^{-\frac{s_1^2}{2n_1\sigma^2}}\cdot \frac{1}{\sqrt{2\pi(n_2-n_1)\sigma}}e^{-\frac{(s_2-s_1)^2}{2(n_2-n_1)\sigma^2}} \end{split}$$

Sum of i.i.d Processes

• If $X_1, X_2, ..., X_n$ are i.i.d and $S_n = X_1 + X_2 + ... + X_n$, we call S_n the sum process of i.i.d, e.g. random walk is a sum process.

$$m_S(n) = E[S_n] = nE[X] = nm$$

 $Var[S_n] = nVar[X] = n\sigma^2$

Autocovariance

$$C_{S}(n,k) = E[(S_{n} - E[S_{n}])(S_{k} - E[S_{k}])]$$

$$= E[(S_{n} - nm)(S_{k} - km)] = E\left[\sum_{i=1}^{n} (X_{i} - m)\sum_{j=0}^{k} (X_{j} - m)\right]$$

$$= \sum_{i=1}^{n} \sum_{j=0}^{k} E[(X_{i} - m)(X_{j} - m)] = \sum_{i=1}^{n} \sum_{j=0}^{k} C_{X}(i,j)$$

$$= \sum_{i=1}^{n} \sum_{j=0}^{k} \sigma^{2} \delta_{ij} = \min(n,k)\sigma^{2}$$

Sum of i.i.d Processes

Example: For random Walk

$$E[S_n] = nm = n(2p - 1)$$

$$Var[S_n] = n\sigma^2 = 4np(1 - p)$$

$$C_S(n, k) = \min(n, k)4p(1 - p)$$

Continuos Time Random Processes

Poisson Process: a good model for arrival process N(t): Number of arrivals in [0,t] λ : arrival rate (average # of arrivals per time unit) We divide [0,t] into n subintervals, each with duration $\delta = \frac{t}{n}$

Assume:

- The probability of more than one arrival in a subinterval is negligible.
- Whether or not an event (arrival) occurs in a subinterval is *independent* of arrivals in other subintervals.

So the arrivals in each subinterval are *Bernoulli* and they are *independent*.

Poisson Process

• Let $p = Prob\{1 \text{ arrival}\}$. Then the average number of arrivals in [0, t] is

$$np = \lambda t \quad \Rightarrow \quad p = \frac{\lambda t}{n}$$

The total arrivals in $[0,t] \sim \mathsf{Bionomial}(n,p)$

$$P[N(t) = k] = \binom{n}{k} p^k (1-p)^k \to \frac{(\lambda t)^k}{k!} e^{-\lambda t}$$

when $n \to \infty$.

Stationary increment? Yes Independent increment? Yes

Poisson Process

ullet Inter-arrival Time: Let T be the inter-arrival time.

$$P\{T>t\}$$
 = $P\{\text{no arrivals in } t \text{ seconds}\}$
 = $P\{N(t)=0\} = e^{-\lambda t}$
 \Rightarrow $P\{T\leq t\} = 1 - e^{-\lambda t}$
 $f_T(t) = \lambda e^{-\lambda t}, \text{ for } t\geq 0$

So the inter-arrival time is exponential with mean $\frac{1}{\lambda}$.

Random Telegraph Signal

Read on your own

• Suppose that the symmetric random walk $(p = \frac{1}{2})$ takes steps of magnitude of h every δ seconds. At time t, we have $n = \frac{t}{\delta}$ jumps.

$$X_{\delta}(t) = h(D_1 + D_2 + \dots + D_n) = hS_n$$

where D_i are *i.i.d* random variables taking ± 1 with equal probability.

$$E[X_{\delta}(t)] = hE[S_n] = 0$$

$$Var[X_{\delta}(t)] = h^2 n Var[D_i] = h^2 n$$

• If we let $h = \sqrt{\alpha \delta}$, where α is a constant and $\delta \to 0$ and let the limit of $X_{\delta}(t)$ be X(t), then X(t) is a continuous-time random process and we have:

$$E[X(t)] = 0$$

$$Var[X(t)] = \lim_{\delta \to 0} h^2 n = \lim_{\delta \to 0} (\sqrt{\alpha \delta})^2 \frac{t}{\delta} = \alpha t$$

X(t) is called the Wiener process. It is used to model Brownian motion, the motion of particles suspended in a fluid that move under the rapid and random impact of neighbooring particles.

• Note that since $\delta = \frac{t}{n}$,

$$X_{\delta}(t) = hS_n = \sqrt{\alpha\delta}S_n = \frac{S_n}{\sqrt{n}}\sqrt{\alpha t}$$

When $\delta \to 0$, $n \to \infty$ and since $\mu_D = 0$, $\sigma_D = 1$, from CLT, we have

$$\frac{S_n}{\sqrt{n}} = \frac{S_n - n\mu_D}{\sigma_D \sqrt{n}} \sim N(0, 1)$$

So the distribution of X(t) follows

$$X(t) \sim N(0, \alpha t)$$

i.e.

$$f_{X(t)}(x) = \frac{1}{\sqrt{2\pi\alpha t}} e^{\frac{-x^2}{2\alpha t}}$$

Since *Wiener process* is a limit of random walk, it inherits the properties such as independent and stationary increments. So the joint pdf of X(t) at t_1, t_2, \dots, t_k ($t_1 < t_2 < \dots < t_k$) will be

$$f_{X(t_1),X(t_2),\cdots,X(t_k)}(x_1,x_2,\cdots,x_k)$$

$$= f_{X(t_1)}(x_1)f_{X(t_2-t_1)}(x_2-x_1)\cdots f_{X(t_k-t_{k-1})}(x_k-x_{k-1})$$

$$= \frac{\exp\{-\frac{1}{2}\left[\frac{x_1^2}{\alpha t_1}+\cdots+\frac{(x_k-x_{k-1})^2}{\alpha (t_k-t_{k-1})}\right]\}}{\sqrt{(2\pi\alpha)^k t_1(t_2-t_1)\cdots(t_k-t_{k-1})}}$$

• mean funtion: $m_X(t) = E[X(t)] = 0$ auto-covariance: $C_X(t_1, t_2) = \alpha \min(t_1, t_2)$ Proof:

$$X_{\delta}(t) = hS_n$$

$$C_{X_{\delta}}(t_1, t_2) = h^2 C_S(n_1, n_2) \quad (\text{where } n_1 = \frac{t_1}{\delta}, n_2 = \frac{t_2}{\delta})$$

$$= (\sqrt{\alpha \delta})^2 \min(n_1, n_2) \sigma_D^2$$

$$(\text{keep in mind that: } \sigma_D^2 = 1)$$

$$= \alpha \min(n_1 \delta, n_2 \delta) = \alpha \min(t_1, t_2)$$

Stationary Random Processes

ullet X(t) is stationary if the joint distribution of any set of samples does not depend on the placement of the time origin.

$$F_{X(t_1),X(t_2),\cdots,X(t_k)}(x_1,x_2,\cdots,x_k)$$

$$=F_{X(t_1+\tau),X(t_2+\tau),\cdots,X(t_k+\tau)}(x_1,x_2,\cdots,x_k)$$
 for all time shift τ , all k , and all choices of t_1,t_2,\cdots,t_k .

• X(t) and Y(t) are *joint stationary* if the joint distribution of $X(t_1), X(t_2), \cdots, X(t_k)$ and $Y(t_1'), Y(t_2'), \cdots, Y(t_j')$ do not depend on the placement of the time origin for all k, j and all choices of t_1, t_2, \cdots, t_k and t_1', t_2', \cdots, t_j' .

Stationary Random Processes

First-Order Stationary

$$F_{X(t)}(x) = F_{X(t+\tau)}(x) = F_X(x),$$
 for all t, τ
 $\Rightarrow m_X(t) = E[X(t)] = m,$ for all t
 $VarX(t) = E[(X(t) - m)^2] = \sigma^2,$ for all t

Second-Order Stationary

$$F_{X(t_1)X(t_2)}(x_1, x_2) = F_{X(0)X(t_2-t_1)}(x_1, x_2),$$
 for all t_1, t_2
 $\Rightarrow R_X(t_1, t_2) = R_X(t_1 - t_2),$ for all t_1, t_2
 $C_X(t_1, t_2) = C_X(t_1 - t_2),$ for all t_1, t_2

The auto-correlation and auto-covariance depend only on the time difference.

Stationary Random Processes

Example:

An i.i.d random process is stationary.

$$F_{X(t_1),X(t_2),\cdots,X(t_k)}(x_1,x_2,\cdots,x_k)$$

$$= F_X(x_1)F_X(x_2)\cdots F_X(x_k)$$

$$= F_{X(t_1+\tau),X(t_2+\tau),\cdots,X(t_k+\tau)}(x_1,x_2,\cdots,x_k)$$

• sum of i.i.d random process $S_n=X_1+X_2+\cdots+X_n$ We know $m_S(n)=nm$ and $Var[S_n]=n\sigma^2$ \Rightarrow not stationary.

Wide-Sense Stationary (WSS)

ullet X(t) is WSS if:

$$m_X(t) = m$$
, for all t $C_X(t_1, t_2) = C_X(t_1 - t_2)$, for all t_1, t_2

Let
$$\tau = t_1 - t_2$$
, then $C_X(t_1, t_2) = C_X(\tau)$.

Wide-Sense Stationary (WSS)

• Example: Let X_n consists of two interleaved sequences of independent r.v.s.

For n even: $X_n \in \{+1, -1\}$ with $p = \frac{1}{2}$

For n odd: $X_n \in \{\frac{1}{3}, -3\}$ with $p = \frac{9}{10}$ and $\frac{1}{10}$ resp.

Obviously, X_n is not stationary, since its pmf varies with n. However,

$$m_X(n) = 0$$
 for all n

$$C_X(i,j) = \begin{cases} E[X_i]E[X_j] = 0, & i \neq j \\ E[X_i^2] = 1, & i = j \end{cases}$$

 $= \delta_{i,j}$
 $\Rightarrow X_n \text{ is WSS.}$

So stationary \Rightarrow WSS, WSS \Rightarrow stationary.

Autocorrelation of WSS processes

- $R_X(0) = E[X^2(t)]$, for all t. $R_X(0)$: average power of the process.
- $R_X(\tau)$ is an even function. $R_X(\tau) = E[X(t+\tau)X(t)] = E[X(t)X(t+\tau)] = R_X(-\tau)$
- ullet $R_X(au)$ is a measure of the rate of change of a r.p.

$$P\{|X(t+\tau) - X(t)| > \varepsilon\} = P\{(X(t+\tau) - X(t))^2 > \varepsilon^2\}$$

$$\leq \frac{E[(X(t+\tau) - X(t))^2]}{\varepsilon^2} \quad \text{(Markov Inequality)}$$

$$= \frac{2[R_X(0) - R_X(\tau)]}{\varepsilon^2}$$

If $R_X(\tau)$ is flat $\Rightarrow [R_X(0) - R_X(\tau)]$ is small \Rightarrow the probability of having a large change in X(t) in τ seconds is small.

Autocorrelation of WSS processes

- $|R_X(\tau)| \le R_X(0)$ Proof: $E[(X(t+\tau) \pm X(t))^2] = 2[R_X(0) \pm R_X(\tau)] \ge 0$ $\Rightarrow |R_X(\tau)| \le R_X(0)$
- If $R_X(0) = R_X(d)$, then $R_X(t)$ is periodic with period d, and X(t) is mean square periodic, i.e.,

$$E[(X(t+d) - X(t))^{2}] = 0$$

Proof: read textbook (pg.360). Use the inequality $E[XY]^2 \le E[X^2]E[Y^2]$ (from $|\rho| \le 1$, sec.4.7)

• If X(t)=m+N(t), where N(t) is a zero-mean process s.t. $R_N(\tau)\to 0$, as $\tau\to\infty$, then $R_X(\tau)=E[(m+N(t+\tau))(m+N(t))]=m^2+R_N(t)\to m^2$ as $\tau\to\infty$.

Autocorrelation of WSS processes

- $R_X(\tau)$ can have three types of components: (1) a component that $\to 0$, as $\tau \to \infty$, (2) a periodic component, and (3) a component that due to a non zero mean.
- Example: $R_X(\tau) = e^{-2\alpha|\tau|}, R_Y(\tau) = \frac{a^2}{2}\cos 2\pi f_0\tau$ If Z(t) = X(t) + Y(t) + m and assume X,Y are independent with zero mean, then

$$R_Z(\tau) = R_X(\tau) + R_Y(\tau) + m^2$$

WSS Gausian Random Process

If a Gaussian r.p. is WSS, then it is stationary (Strict) Sense Stationary) Proof:

$$f_{\underline{X}}(\underline{x}) = \frac{\exp\{-\frac{1}{2}(\underline{x} - \underline{m})^T K^{-1}(\underline{x} - \underline{m})\}}{(2\pi)^{\frac{n}{2}} |K|^{\frac{1}{2}}}$$

$$f_{\underline{X}}(\underline{x}) = \frac{\exp\{-\frac{1}{2}(\underline{x} - \underline{m})^T K^{-1}(\underline{x} - \underline{m})\}}{(2\pi)^{\frac{n}{2}} |K|^{\frac{1}{2}}}$$

$$\underline{m} = \begin{bmatrix} m_X(t_1) \\ \vdots \\ m_X(t_n) \end{bmatrix} K = \begin{bmatrix} C_X(t_1, t_1) & \cdots & C_X(t_1, t_n) \\ \vdots & \vdots & \vdots \\ C_X(t_n, t_1) & \cdots & C_X(t_n, t_n) \end{bmatrix}$$

If X(t) is WSS, then $m_X(t_1) = m_X(t_2) = \cdots = m$, $C_X(t_i,t_j)=C_X(t_i-t_j)$. So $f_X(\underline{x})$ does not depend on the choice of the time origin ⇒ Strict Sense Stationary.

Cyclo Stationary Random Process

Read on your own.



- Recall that for $X_1, X_2, \cdots, X_n, \cdots$ $X_n \to X$ in m.s. (mean square) if $E[(X_n - X)^2] \to 0$, as $n \to \infty$
- Cauchy Criterion If $E[(X_n-X_m)^2]\to 0$ as $n\to\infty$ and $m\to\infty$, then $\{X_n\}$ converges in m.s.
- Mean Square Continuity The r.p. X(t) is continuous at $t=t_0$ in m.s. if $E[(X(t)-X(t_0))^2]\to 0$, as $t\to t_0$ We wrtie it as: $\lim_{t\to t_0} X(t)=X(t_0)$ (limit in the mean)



$$E[(X(t)-X(t_0))^2] = R_X(t,t)-R_X(t_0,t)-R_X(t,t_0)+R_X(t_0,t_0)$$

If $R_X(t_1,t_2)$ is continuous (both in t_1,t_2), at point (t_0,t_0) , then $E[(X(t)-X(t_0))^2] \to 0$. So $X(t)$ is continuous at t_0 in m.s. if $R_X(t_1,t_2)$ is continuous at (t_0,t_0)

• If X(t) is WSS, then:

$$E[(X(t_0 + \tau) - X(t_0))^2] = 2(R_X(0) - R_X(\tau))$$

So X(t) is continuous at t_0 , if $R_X(\tau)$ is continuous at $\tau=0$

• If X(t) is continuous at t_0 in m.s., then

$$\lim_{t \to t_0} m_X(t) = m_X(t_0)$$

Proof:

$$Var[X(t) - X(t_0)] \ge 0$$

$$\Rightarrow E[X(t) - X(t_0)]^2 \le E[(X(t) - X(t_0))^2] \to 0$$

$$\Rightarrow (m_X(t) - m_X(t_0))^2 \to 0$$

$$\Rightarrow m_X(t) \to m_X(t_0)$$

Example: Wiener Process:

$$R_X(t_1, t_2) = \alpha \min(t_1, t_2)$$

 $R_X(t_1,t_2)$ is continous at $(t_0,t_0)\Rightarrow X(t)$ is continuous at t_0 in m.s.

Example: Poisson Process:

$$C_N(t_1, t_2) = \lambda \min(t_1, t_2)$$

$$R_N(t_1, t_2) = \lambda \min(t_1, t_2) + \lambda^2 t_1 t_2$$

N(t) is continuous at t_0 in m.s.

Note that for any sample poisson process, there are infinite number of discontinuities, but N(t) is continuous at any t_0 in m.s.

Mean Square Derivative

• The mean square derivative X'(t) of the r.p. X(t) is defined as:

$$X'(t) = \lim_{\varepsilon \to 0} \frac{X(t+\varepsilon) - X(t)}{\varepsilon}$$

provided that

$$\lim_{\varepsilon \to 0} E\left[\left(\frac{X(t+\varepsilon) - X(t)}{\varepsilon} - X'(t)\right)^2\right] = 0$$

- The mean square derivative of X(t) at t exists if $\frac{\partial^2}{\partial t_1 \partial t_2} R_X(t_1, t_2)$ exists at point (t, t). Proof: read on your own.
- For a Gaussian random process X(t), X'(t) is also Gaussian

Mean Square Derivative

ullet Mean, cross-correlation, and auto-correlation of X'(t)

$$m_{X'}(t) = \frac{d}{dt} m_X(t)$$

$$R_{XX'}(t_1, t_2) = \frac{\partial}{\partial t_2} R_X(t_1, t_2)$$

$$R'_X(t_1, t_2) = \frac{\partial^2}{\partial t_1 \partial t_2} R_X(t_1, t_2)$$

ullet When X(t) is WSS,

$$m_{X'}(t) = 0$$

$$R_{XX'}(\tau) = \frac{\partial}{\partial t_2} R_X(t_1 - t_2) = -\frac{d}{d\tau} R_X(\tau)$$

$$R_{X'}(\tau) = \frac{\partial}{\partial t_1} \left\{ \frac{\partial}{\partial t_2} R_X(t_1 - t_2) \right\} = -\frac{d^2}{d\tau^2} R_X(\tau)$$

Mean Square Derivative

Example: Wiener Process

$$R_X(t_1, t_2) = \alpha \min(t_1, t_2) \Rightarrow \frac{\partial}{\partial t_2} R_X(t_1, t_2) = \alpha u(t_1 - t_2)$$

 $u(\cdot)$ is the step function and is discontinuous at $t_1=t_2$. If we use the delta function,

$$R_{X'}(t_1, t_2) = \frac{\partial}{\partial t_1} \alpha u(t_1, t_2) = \alpha \delta(t_1 - t_2)$$

Note X'(t) is not physically feasible since $E[X'(t)^2] = \alpha \delta(0) = \infty$, i.e., the signal has infinite power. When $t_1 \neq t_2$, $R_{X'}(t_1, t_2) = 0 \Rightarrow X'(t_1), X'(t_2)$ uncorrelated (note $m_{X'}(t) = 0$ for all t) \Rightarrow independent since X'(t) is a Gaussian process.

Mean Square Integrals

- The mean square integral of X(t) form t_0 to t: $Y(t) = \int_{t_0}^t X(t') dt' \text{ exists if the integral}$ $\int_{t_0}^t \int_{t_0}^t R_X(u,v) du dv \text{ exists.}$
- $lue{}$ The mean and autocorrelation of Y(t)

$$m_Y(t) = \int_{t_0}^t m_X(t')dt'$$
 $R_Y(t_1, t_2) = \int_{t_0}^{t_1} \int_{t_0}^{t_2} R_X(u, v)dudv$

Ergodic Theorems

 Time Averages of Random Processes and Ergodic Theorems.

Read on your own.