

MECH 343/2 X: Theory of Machines I.
Solution to Assignment #7.

1. $N_2 = 20$, $N_3 = 60$, $P = 6 \text{ teeth/in}$

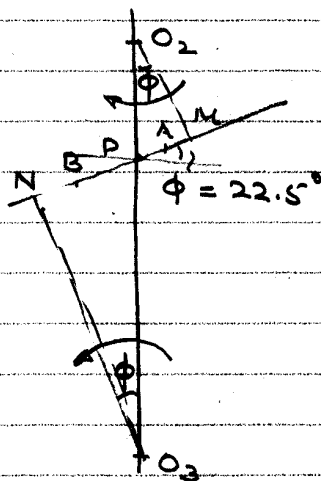
(a) $P = \frac{N}{D}$ $D_2 = \frac{N_2}{P} = \frac{20}{6} = 3.3333''$
 $D_3 = \frac{N_3}{P} = \frac{60}{6} = 10.0''$

$m = \frac{D}{N} = \frac{1}{6} \text{ in}$

$p = \frac{\pi D}{N} = \pi m = 0.5236''$

$C = \frac{1}{2}(D_2 + D_3) = 6.6667''$

(b)



$a_2 = a_3 = 1 \text{ in} = 0.1667''$

$O_2P = R_2 = \frac{1}{2}D_2 = 1.6667''$

$O_3P = R_3 = \frac{1}{2}D_3 = 5.0''$

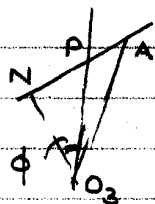
$O_3A = R_3 + a_3 = 5.1667''$

$O_2B = R_2 + a_2 = 1.8333''$

$PM = R_2 \sin \phi = 0.6378''$

$PN = R_3 \sin \phi = 1.9134''$

Contact begins at A



$AN = \sqrt{O_3A^2 - O_3N^2}$

$= \sqrt{5.1667^2 - (5 \cos 22.5)^2} = 2.3142''$

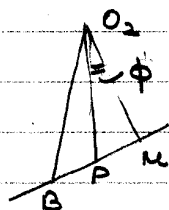
$AP = AN - PN$

$= 2.3142 - 1.9134 = 0.4008''$

$AP < PM$

(2)

Contact ends at B



$$BM = \sqrt{O_2B^2 - O_2M^2}$$

$$= \sqrt{1.8333^2 - (1.6667 \cos 22.5^\circ)^2}$$

$$= 0.9951 \text{ m}$$

$$BP = BM - PM$$

$$= 0.9951 - 0.6378 = 0.3572''$$

$$BP < PN$$

Since $AP < PM$ & $BP < PN$ No interference.

Path of contact = AB

$$= AP + BP = 0.4008 + 0.3572$$

$$\therefore u = 0.7580 \text{ in.}$$

$$\text{Arc of contact} = \frac{u}{\cos \phi} = 0.8205 \text{ m}$$

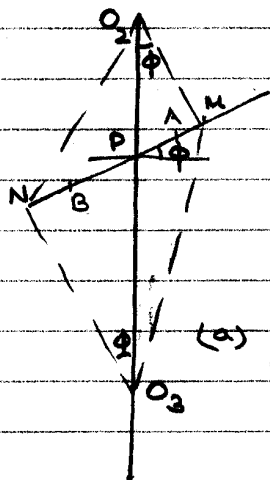
$$\therefore q = 0.8205 \text{ m}$$

$$\left. \begin{array}{l} \text{Average number} \\ \text{of tooth pair} \\ \text{in contact} \end{array} \right\} = \frac{q}{p} = \frac{0.8205}{0.5236} = 1.567$$

$$m_c = 1.567 > 1$$

 $\therefore$ Continuous contact is ensured.

2.



For no interference,

$$R_2 + a_2 < O_2N$$

$$R_3 + a_3 < O_3M$$

$$R_2 = \frac{1}{2} D_2 = 50 \text{ mm}$$

$$R_3 = \frac{1}{2} D_3 = 90 \text{ mm}$$

$$\therefore a_2 < \sqrt{O_2M^2 + NM^2} - R_2$$

$$a_3 < \sqrt{O_3N^2 + NM^2} - R_3$$

$$\text{Now } O_2M = R_2 \cos \phi = 46.194 \text{ mm}$$

$$PM = R_2 \sin \phi = 19.134 \text{ mm}$$

$$O_3N = R_3 \cos \phi = 83.149 \text{ mm}$$

$$PN = R_3 \sin \phi = 34.442 \text{ mm}$$

$$NM = PN + PM = 53.576 \text{ mm}$$

Miles

(3)

$$\therefore a_2 < \sqrt{16.194^2 + 53.576^2} - 50 = 20.741 \text{ mm}$$

$$a_3 < \sqrt{83.149^2 + 53.576^2} - 90 = 8.915 \text{ mm}$$

$$\therefore a < 20.741, a < 8.915$$

$$\therefore a_{\max} = 8.915 \quad (\text{This corresponds to } \omega_{\text{Real}})$$

(b).

$$a = 1 \text{ m}$$

$$= \frac{D}{N}$$

$$\therefore \frac{D}{N} < a_{\max}$$

$$\therefore N_2 > \frac{D_2}{a_{\max}} = 11.22$$

$$N_3 > \frac{D_3}{a_{\max}} = 20.19$$

$\therefore N_2$ must be at least 12.

N_3 must be at least 21.

$$\text{In order to maintain } \frac{N_3}{N_2} = \frac{D_3}{D_2} = 2.$$

$$N_2 > 12$$

$$N_3 > 22.$$

(c)

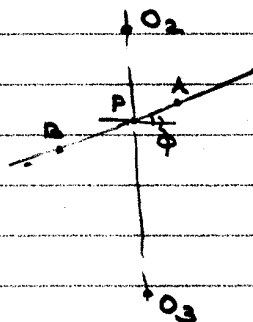
$$a = \frac{D_2}{N_2} = \frac{D_3}{N_3}$$

$$\therefore a = \frac{100}{12} = 8.333 \text{ mm}$$

(For design, the largest available standard addendum which is smaller than 8.333 mm must be chosen. $\therefore a = 8 \text{ mm}$)

For this problem:

$$a = 8.333 \text{ mm}$$



$$AP = \sqrt{98.333^2 - (90 \cos 22.5^\circ)^2} - 90 \sin 22.5^\circ$$

$$= 18.052 \text{ mm}$$

$$BP = \sqrt{58.333^2 - (50 \cos 22.5^\circ)^2} - 50 \sin 22.5^\circ$$

$$= 16.487 \text{ mm}$$

$$r = 18.052 + 16.487 = 35.539 \text{ mm}$$

$$q = \frac{r}{\cos \phi} = 37.385 \text{ mm}$$

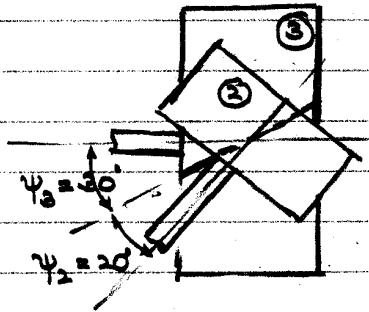
$$p = r \tan \phi = 26.179 \text{ mm}$$

④

$$\therefore m_c = \frac{q}{p} = 1.428 > 1.$$

$\therefore$ Contact is ensured.

3.



Note: The pinion and wheel are left handed.

$$\Sigma = \psi_2 + \psi_3 = 50^\circ$$

(a) $p_n = \frac{\pi D}{N} \cos \psi = \text{normal pitch.}$

$$\therefore \text{normal module} \left\} = \frac{D \cos \psi}{N} = m_n$$

$$\text{normal diametral pitch} \left\} = \frac{N}{D \cos \psi} = P_n$$

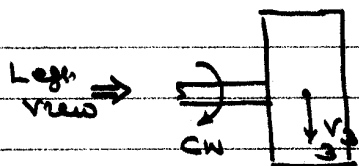
$$\therefore D = \frac{N}{P_n \cos \psi}$$

$$D_2 = \frac{N_2}{P_n \cos \psi_2} = \frac{30}{5 \cos 20^\circ} = 6.3851''$$

$$D_3 = \frac{N_3}{P_n \cos \psi_3} = \frac{60}{5 \cos 30^\circ} = 13.8564''$$

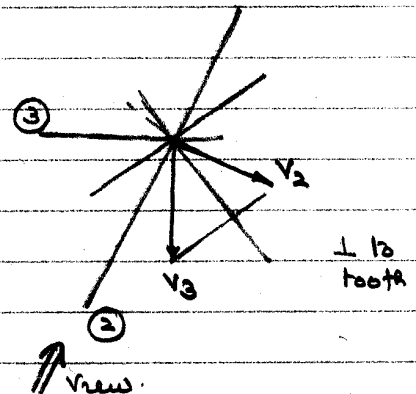
(b) $C = \frac{1}{2} (D_2 + D_3) = 10.1208''$

(c) Wheel.



$$V_3 = \frac{1}{2} D_3 \omega_3 = 181.38''/s$$

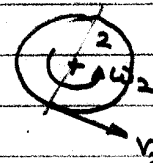
$$\omega_3 = \frac{250 \times 2\pi}{60} \text{ rad/s} = 26.180 \text{ rad/s}$$



$$V_2 \cos \psi_2 = V_3 \cos \psi_3$$

$$\therefore V_2 = \frac{V_3 \cos \psi_3}{\cos \psi_2} = 167.16''/s$$

$$\omega_2 = \frac{V_2}{\frac{1}{2} D_2} = 52.360 \text{ rad/s}$$



$\therefore \omega_2$ is CCW

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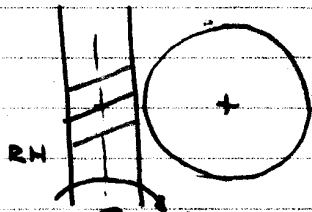
Note: $\frac{\omega_2}{\omega_3} = \frac{N_3}{N_2} = \frac{60}{30} = 2$

$$V_3 = V_2 \sin \psi_2 + V_3 \sin \psi_3$$

$$= 167.16 \sin 20 + 181.38 \sin 30$$

$$= 147.86 \text{ m/s} = 12.321 \text{ m/s}$$

4.



$\lambda = 30^\circ$

$\therefore \psi_2 = 90^\circ - 30^\circ$
 $= 60^\circ$

$\Sigma = \psi_2 + \psi_3$

$\therefore \psi_3 = 30^\circ$

(b) For Worm:

Axial pitch $= \frac{1}{2}$ (This must be given)

$\therefore \text{Lead} = N p_a = 3 \left(\frac{1}{2} \right) = 1.5$

$\tan \lambda = \frac{\text{Lead}}{\pi D}$

$\therefore D_2 = \frac{1.5}{\pi \tan 30^\circ} = 0.8270$

For Wheel:

$\frac{\omega_2}{\omega_3} = \frac{N_3}{N_2}$

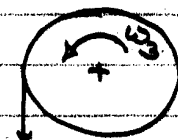
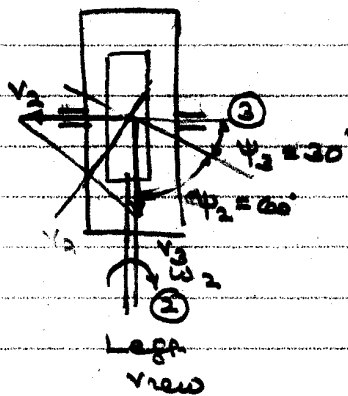
$\therefore 15 = \frac{N_3}{16}$

$\therefore N_3 = 240$

$\therefore \frac{D_3 \cos \psi_3}{N_3} = \frac{D_2 \cos \psi_2}{N_2}$

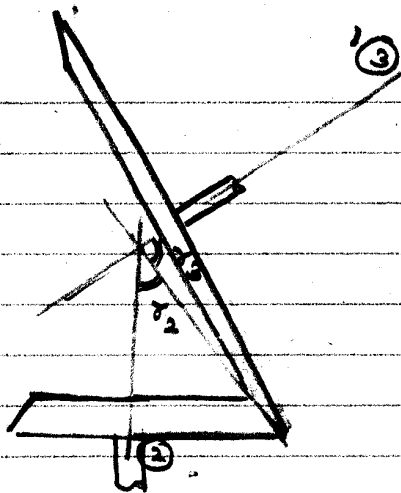
$\therefore D_3 = \frac{D_2 \cos \psi_2}{\cos \psi_3} \cdot \frac{N_3}{N_2}$
 $= 7.1620$

(c)



$\therefore$ In the front view
 (3) rotates in
 CCW sense.
 V_3 is downward.

$\frac{\omega_3}{\omega_2} = \frac{N_2}{N_3} \therefore \omega_3 = \left(\frac{16}{240} \right) \omega_2$
 $= 100 \text{ RPM}$



For bevel gears,

$$\frac{P_3}{P_2} = \frac{\sin \gamma_3}{\sin \gamma_2}$$

and

$$\frac{\omega_2}{\omega_3} = \frac{P_3}{P_2} = \frac{N_3}{N_2}$$

$$N_2 = 15 \quad N_3 = 33$$

$$\therefore \frac{N_3}{N_2} = \frac{33}{15} = 2.2 \quad \text{Reduction Ratio}$$

(a)

$$\therefore \frac{\sin \gamma_3}{\sin \gamma_2} = 2.2$$

$$\therefore \sin (120 - \gamma_2) = (2.2) (\sin \gamma_2)$$

$$(\sin 120)(\cos \gamma_2) - (\cos 120)(\sin \gamma_2) = (2.2)(\sin \gamma_2)$$

$$\therefore \tan \gamma_2 = \frac{\sin 120^\circ}{2.2 + \cos 120^\circ} = 0.5094$$

$$\gamma_2 = 26.996^\circ$$

$$\gamma_3 = 120 - \gamma_2 = 93.004^\circ$$

(b)

$$p = \frac{\pi D_2}{N_2} = \frac{\pi D_3}{N_3}$$

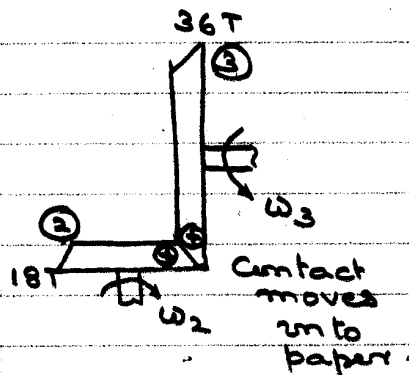
p = circumferential pitch.

$$D_2 = \frac{p N_2}{\pi} = \frac{(15)(15)}{\pi} = 71.620 \text{ mm}$$

$$D_3 = \frac{p N_3}{\pi} = \frac{(15)(33)}{\pi} = 157.563 \text{ mm}$$

Widrow

6. Bevel Gears:

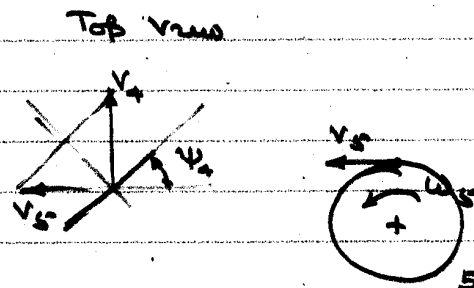
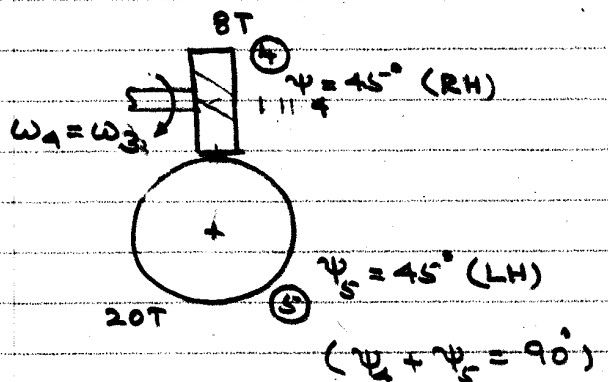


$$\frac{\omega_3}{\omega_2} = \frac{Z_2}{Z_3}$$

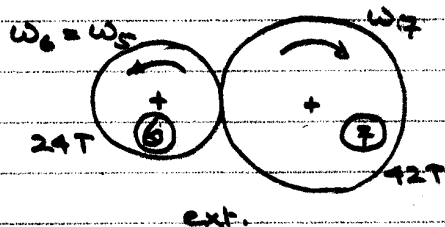
$$\omega_3 = \frac{18}{36} \times 1050$$

$$= 525 \text{ RPM.}$$

Worm & Wheel:



Spur. gear:



$$\frac{\omega_5}{\omega_4} = \frac{Z_4}{Z_5}$$

$$\omega_5 = \frac{8}{20} \times 525$$

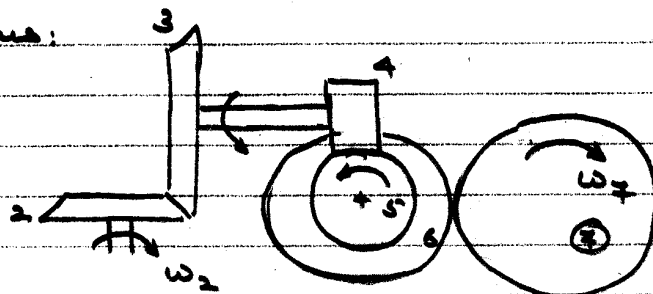
$$= 210 \text{ RPM.}$$

$$\frac{\omega_7}{\omega_6} = \frac{Z_6}{Z_7}$$

$$\therefore \omega_7 = \frac{24}{42} \times 210$$

$$= 120 \text{ RPM.}$$

Thus:



$$\text{Gear ratio} = \frac{\omega_7}{\omega_2} = \frac{120}{1050} = 0.1143 < 1$$

∴ Reduction Gear

$$\therefore \text{Reduction ratio} = \frac{\omega_2}{\omega_7} = \frac{1050}{120} = 8.75$$

Alibay